

Null controllability of the Grushin equation : non-rectangular control region

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- 1 **Controllability of the heat equation**
- 2 **Controllability of the Grushin equation**
- 3 **Comments and open problems**

Notions of controllability

Problematic

We search \mathbf{u} , called **control**, such that the solution f to system

$$\begin{cases} \partial_t f = \mathcal{A}(f) + \mathcal{B}(\mathbf{u}) \\ f(0) = f^0 \end{cases}$$

satisfies :

- f near a given target at time T

$$\forall \varepsilon > 0, f^0, f^1, \exists \mathbf{u} \text{ s.t. } d(f(T), f^1) \leq \varepsilon.$$

➤ **Approximate controllability**

- f reach a target at time T

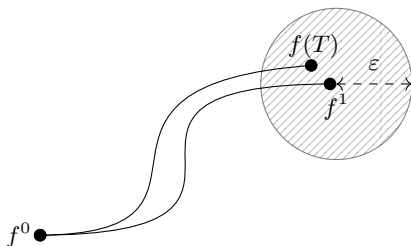
$$\forall f^0, f^1, \exists \mathbf{u} \text{ s.t. } f(T) = f^1.$$

➤ **Exact controllability**

- f reach a target at time T

$$\forall f^0, f^1, \exists \mathbf{u} \text{ s.t. } f(T) = 0.$$

➤ **Null controllability**

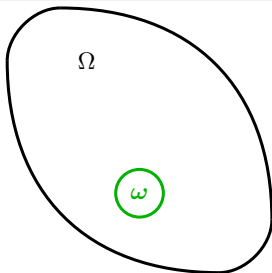


Internal null controllability of the heat equation

Let Ω be an open bounded set of \mathbb{R}^n ,
 ω an non-empty open set of Ω
and $T > 0$.

Consider the heat equation

$$\begin{cases} \partial_t f - \Delta f = \mathbf{1}_\omega u, \\ f|_{\partial\Omega} = 0, \\ f(0) = f^0. \end{cases} \quad (1)$$



Theorem (Internal null controllability of the heat equation)

The heat equation (1) is **null controllable** at time T , i.e. for each initial condition $f^0 \in L^2(\Omega)$, there exists a control $u \in L^2([0, T] \times \omega)$ such that solution f to (1) satisfies $f(T) = 0$.

→ Fattorini-Russell 71' (dim 1) : moment method

→ Fursikov-Imanuvilov / Lebeau-Robbiano 95' : Carleman inequality / spectral inequality

Remark

- **No minimal time** of controllability
- **No geometrical condition** on ω

Boundary null controllability of the heat equation

Let Ω be an open bounded set of \mathbb{R}^n , γ an non-empty open set of $\partial\Omega$ and $T > 0$.

$$\begin{cases} \partial_t f - \Delta f = 0, \\ f|_{\partial\Omega} = \mathbf{1}_\gamma u, \\ f(0) = f^0. \end{cases} \quad (2)$$

Corollary (Boundary null controllability of the heat equation)

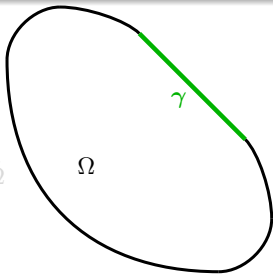
The heat equation (2) is **null controllable** at time T , i.e. for each initial condition $f^0 \in L^2(\Omega)$, there exists a control $u \in L^2([0, T] \times \gamma)$ such that solution f to (2) satisfies $f(T) = 0$.

Sketch of proof : the fictitious control method

- Extension $\tilde{\Omega}$ of Ω through γ
- $\omega \subset \tilde{\Omega}$
- $\tilde{f} :=$ solution of the int. contr. problem on $\Omega \cup \tilde{\Omega}$
- $u := \tilde{f}|_\gamma$

Remark

- **Equivalence between internal and boundary null controllability**



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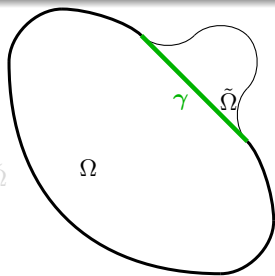
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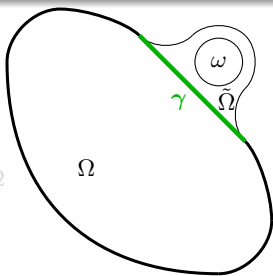
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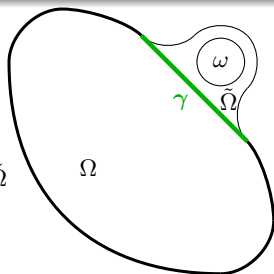
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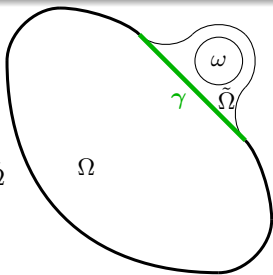
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Corollary (Boundary null controllability of the heat equation)

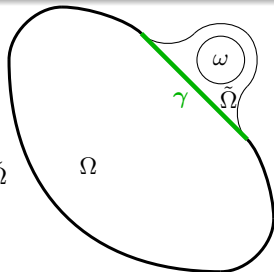
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- $u := \tilde{f}|_{\gamma}$

Remark

- **Equivalence between internal and boundary** null controllability



Duality

Denote by $f(t; f^0, \mathbf{u})$ the solution to

$$\begin{cases} \partial_t f - \Delta f = \mathbf{1}_\omega \mathbf{u}, \\ f|_{\partial\Omega} = 0, \\ f(0) = f^0. \end{cases} \quad (1)$$

Let $Q_T := \Omega \times (0, T)$ and

$$\begin{aligned} F_T : L^2(\Omega) &\rightarrow L^2(\Omega), & G_T : L^2(Q_T) &\rightarrow L^2(\Omega), \\ f^0 &\mapsto f(T; f^0, 0) & \mathbf{u} &\mapsto f(T; 0, \mathbf{u}) \end{aligned}$$

One has :

$$\begin{aligned} \text{Null controllability of (1)} &\Leftrightarrow \forall f^0, \exists \mathbf{u} : F_T(f^0) + G_T(\mathbf{u}) = 0 \\ &\Leftrightarrow \text{Im}(F_T) \subset \text{Im}(G_T) \\ &\Leftrightarrow \|F_T^* \varphi^T\| \leq C \|G_T^* \varphi^T\|, \forall \varphi^T \end{aligned}$$

$$\begin{aligned} \text{Approximate controllability of (1)} &\Leftrightarrow \overline{\text{Im}(G_T)} = L^2(\Omega) \\ &\Leftrightarrow (G_T^* \varphi^T = 0 \Rightarrow \varphi^T = 0), \forall \varphi^T \end{aligned}$$

$$\left\{ \begin{array}{l} \partial_t f - \Delta f = \mathbf{1}_\omega u, \\ f|_{\partial\Omega} = 0, \\ f(0) = f^0. \end{array} \right. \quad (1) \quad \left\{ \begin{array}{ll} -\partial_t \varphi = \Delta \varphi & \text{in } Q_T, \\ \varphi = 0 & \text{on } \Sigma_T, \\ \varphi(T) = \varphi^T & \text{in } \Omega. \end{array} \right.$$

Proposition (see Coron's book 2007 or Tucsnak-Weiss's book 2009)

- ① System (1) is **null controllable** on $(0, T)$, if and only if there exists $C_{obs} > 0$ such that for all $\varphi^T \in L^2(\Omega)$

$$\|\varphi(0)\|_{L^2(\Omega)} \leq C_{obs} \int_0^T \|\varphi\|_{L^2(\omega)} dt$$

with φ the solution to the dual system.

- ② System (1) is **approx. controllable** at time T , if and only if for all $\varphi^T \in L^2(\Omega)$ the solution to the dual system satisfies

$$\varphi = 0 \text{ in } \omega \times (0, T) \Rightarrow \varphi = 0 \text{ in } Q_T.$$

Approximate controllability of the heat equation

$$\begin{cases} \partial_t f - \Delta f = \mathbf{1}_\omega \mathbf{u} & \text{in } Q_T, \\ f|_{\partial\Omega} = 0 & \text{on } \Sigma_T, \\ f(0) = f^0 & \text{in } \Omega. \end{cases} \quad (1) \quad \begin{cases} -\partial_t \varphi = \Delta \varphi & \text{in } Q_T, \\ \varphi = 0 & \text{on } \Sigma_T, \\ \varphi(T) = \varphi^T & \text{in } \Omega. \end{cases}$$

Since (1) is null controllable,

$$\|\varphi(0)\|_{L^2(\Omega)} \leq C_{obs} \int_0^T \|\varphi\|_{L^2(\omega)} dt$$

Hence

$$\begin{aligned} \varphi = 0 \text{ in } \omega \times (0, T) &\Rightarrow \varphi(0) = 0 \text{ in } \Omega \\ &\Rightarrow \varphi = 0 \text{ in } \Omega \times (0, T) \end{aligned}$$

Corollary (Approximate controllability of the heat equation)

The heat equation (1) is **approx. controllable** at time T , i.e. for each $f^0, f^1 \in L^2(\Omega)$, there exists a control $\mathbf{u} \in L^2([0, T] \times \omega)$ such that solution f to (1) satisfies $\|f(T) - f^1\| \leq \varepsilon$.

Conclusion

- **Non exact controllability**
 - Regularizing effect of the heat equation
- **Null controllability**
 - Equivalence of int. and bound. null contr. thanks to fictitious control method
- **Approximate controllability**
 - Come from the null controllability thanks to the duality

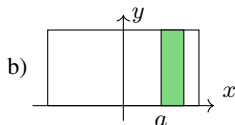
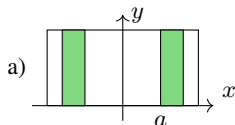
Question

How a modification of $-\Delta$ can influx these notions of controllability ?

The Grushin equation

Consider

$$\begin{cases} (\partial_t - \partial_x^2 - x^2 \partial_y^2) f(t, x, y) = \mathbf{1}_\omega u & t \in [0, T], (x, y) \in \Omega := (-1, 1) \times (0, 1), \\ f(t, x, y) = 0 & t \in [0, T], (x, y) \in \partial\Omega, \\ f(0, x, y) = f^0(x, y) & (x, y) \in \Omega, \end{cases}$$



a) minimal time of internal null controllability $T^* = a^2/2$

➤ Beauchard-Miller-Morancey 2015

b) minimal time of internal null controllability $T^* > a^2/2$

➤ Beauchard-Cannarsa-Guglielmi 2014

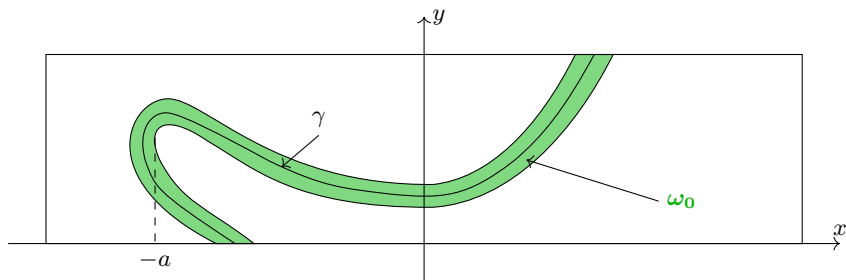
minimal time of boundary null controllability $T^* = a^2/2$

➤ Beauchard-Dardé-Ervedoza 2018

c) No internal null controllability

➤ Koenig 2017

Positive result



Theorem (D.-Koenig)

Assume that there exist $\varepsilon > 0$ and $\gamma \in C^0([0, 1], \Omega)$ with $\gamma(0) \in (-1, 1) \times \{0\}$ and $\gamma(1) \in (-1, 1) \times \{\pi\}$ such that

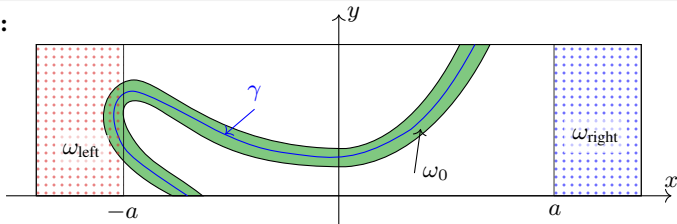
$$\omega_0 := \{z \in \Omega, \text{distance}(z, \text{Range}(\gamma)) < \varepsilon\} \subset \omega,$$

then the Grushin equation is **null-controllable** in any time $T > a^2/2$, where

$$a := \sup_{(x,y) \in \Omega \setminus \omega_0} \{|x| : \exists x_0 \in (-1, 1), |x| < |x_0|, \text{sgn}(x) = \text{sgn}(x_0), (x_0, y) \in \omega_0\}.$$

Positive result : sketch of proof

Proof :



Consider that controlled solutions [Beauchard Darde Ervedoza 2018]

$$\begin{cases} (\partial_t - \partial_x^2 - x^2 \partial_y^2) f_{\text{left}} = \mathbf{1}_{\omega_{\text{left}}} u_{\text{left}} & \text{on } [0, T] \times \Omega \\ (\partial_t - \partial_x^2 - x^2 \partial_y^2) f_{\text{right}} = \mathbf{1}_{\omega_{\text{right}}} u_{\text{right}} & \text{on } [0, T] \times \Omega \\ f_{\text{left}}(0) = f_{\text{right}}(0) = f_0, f_{\text{left}}(T) = f_{\text{right}}(T) = 0 & \text{on } \Omega \end{cases}$$

There exists a function $\theta \in C^\infty(\bar{\Omega})$ such that

$$\theta = 0 \text{ on } \omega_{\text{left}} \setminus \omega_0, \theta = 1 \text{ on } \omega_{\text{right}} \setminus \omega_0, \text{supp}(\nabla \theta) \subset \omega_0.$$

We remark that $f := \theta f_{\text{left}} + (1 - \theta) f_{\text{right}}$, solves

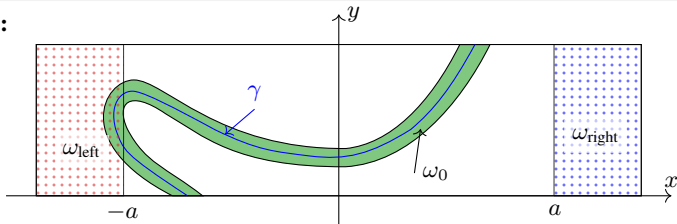
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where $u := \theta \mathbf{1}_{\omega_{\text{left}}} u_{\text{left}} + (1 - \theta) \mathbf{1}_{\omega_{\text{right}}} u_{\text{right}} + (f_{\text{right}} - f_{\text{left}})(\partial_x^2 + x^2 \partial_y^2) \theta + 2\partial_x(f_{\text{right}} - f_{\text{left}})\partial_x \theta + 2x^2 \partial_y(f_{\text{right}} - f_{\text{left}})\partial_y \theta.$

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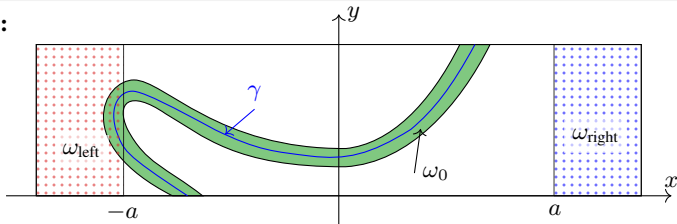
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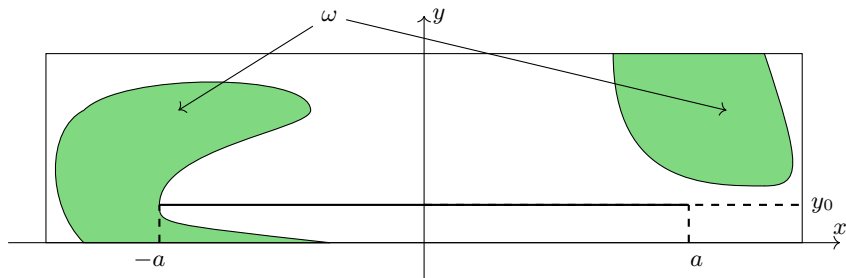
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□

Negative result



Theorem (D.-Koenig)

If for some $y_0 \in (0, \pi)$ and $a > 0$ one has

$$\{(x, y_0), -a < x < a\} \cap \bar{\omega} = \emptyset,$$

then the Grushin equation is **not null controllable** in time $T < a^2/2$.

Remark : Since the Grushin equation is not null-controllable when ω is the complement of a horizontal strip [Koenig 2017], our Assumption is quasi optimal.

Proposition (see Coron's book 2007 or Tucsnak-Weiss's book 2009)

The Grushin equation is **null controllability** if, and only if, there exists $C > 0$ such that for all f_0 in $L^2(\Omega)$, the solution f to

$$\begin{cases} (\partial_t - \partial_x^2 - x^2 \partial_y^2) f(t, x, y) = 0 & t \in [0, T], (x, y) \in \Omega, \\ f(t, x, y) = 0 & t \in [0, T], (x, y) \in \partial\Omega, \\ f(0, x, y) = f_0(x, y) & (x, y) \in \Omega, \end{cases}$$

satisfies

$$\int_{\Omega} |f(T, x, y)|^2 dx dy \leq C \int_{[0, T] \times \omega} |f(t, x, y)|^2 dt dx dy.$$

Negative result : sketch of proof

Assume that $\Omega = \mathbb{R} \times \mathbb{T}$.

For $n > 0$,

$e^{-nx^2/2}$ is the first eigenfunction of $-\partial_x^2 + (nx)^2$

and with associated eigenvalue n .

Then

$e^{-nx^2/2} e^{iny}$ is an eigenfunction of $-\partial_x^2 - x^2 \partial_y^2$

and with eigenvalue n .

For the functions

$$f(t, x, y) = \sum a_n e^{-nt + iny - nx^2/2},$$

the observability inequality reads :

$$\sum \left(\frac{2\pi}{n}\right)^{1/2} |a_n|^2 e^{-2nT} \leq C \int_{[0, T] \times \omega} \left| \sum a_n e^{-nt + iny - nx^2/2} \right|^2 dt dx dy$$

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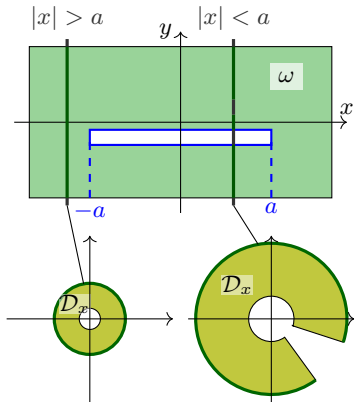
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Negative result : sketch of proof

Consider the change of variable $z_x(t, y) := e^{-t+iy-x^2/2}$

and denote $\mathcal{D}_x := \{e^{-x^2/2-t+iy}, 0 < t < T, (x, y) \in \omega\}$:

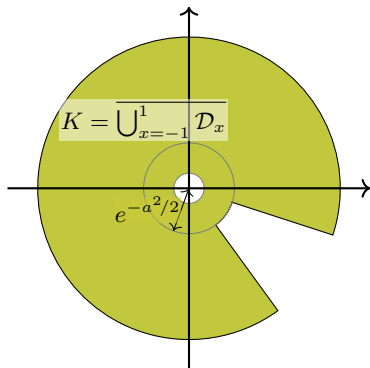
$$\int_{[0, T] \times \omega} \left| \sum a_n e^{iny-nt-nx^2/2} \right|^2 dt dx dy = \int_{-1}^1 \int_{\mathcal{D}_x} \left| \sum_{n>0} a_n z^{n-1} \right|^2 d\lambda(z) dx.$$



Negative result : sketch of proof

Thus

$$\int_{D(0, e^{-T})} \left| \sum_{n>0} a_n z^{n-1} \right|^2 d\lambda(z) \leq C \left| \sum_{n>0} a_n z^{n-1} \right|_{L^\infty(K)}.$$



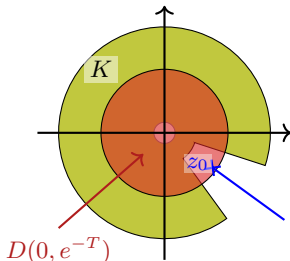
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Let $z_0 \in D(0, e^{-T}) \setminus \overline{K}$

and

$$f : z \in \mathbb{C} \setminus z_0[1, +\infty) \mapsto (z - z_0)^{-1}.$$



Proposition (Runge's theorem)

Let K be a connected and simply connected open subset of \mathbb{C} , and let f be a holomorphic function on K . There exists a sequence (p_k) of polynomials that converges uniformly on every compact subsets of K to f .

Then, the family p_k is a counter example to the inequality on entire polynomials. \square

Negative result : sketch of proof

Assume now that $\Omega = (-1, 1) \times (0, 1)$.

For $n > 0$, let us note

v_n the first eigenfunction of $-\partial_x^2 + (nx)^2$

with Dirichlet boundary condition on $(-1, 1)$, and with associated eigenvalue λ_n .

Then

$v_n(x) \sin(ny)$ is an eigenfunction of $-\partial_x^2 - x^2 \partial_y^2$

with Dirichlet boundary condition on $\partial\Omega$, and with eigenvalue λ_n .

For the functions

$$f(t, x, y) = \sum a_n v_n(x) e^{-\lambda_n t} \sin(ny),$$

the observability inequality reads :

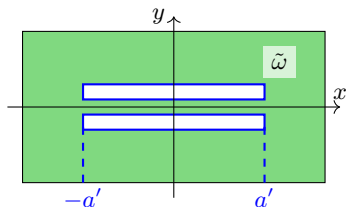
$$\sum |a_n|^2 |v_n|_{L^2}^2 e^{-2\lambda_n T} \leq C \int_{[0, T] \times \omega} \left| \sum a_n v_n(x) e^{-\lambda_n t} \sin(ny) \right|^2 dt dx dy$$

Let us estimate the right hand-side of this inequality

Negative result : sketch of proof

- Noting $\tilde{\omega} = \omega \cup \{(x, -y), (x, y) \in \omega\}$, this implies

$$\begin{aligned} & \int_{[0,T] \times \omega} \left| \sum a_n v_n(x) e^{-\lambda_n t} \sin(ny) \right|^2 dt dx dy \\ & \leq C \int_{[0,T] \times \tilde{\omega}} \left| \sum a_n v_n(x) e^{iny - \lambda_n t} \right|^2 dt dx dy. \end{aligned}$$



Negative result : sketch of proof

- Consider the change of variable

$$\begin{cases} \lambda_n = n + \rho_n \\ v_n(x) = e^{-(1-\varepsilon)nx^2/2} w_n(x) \\ z_x(t, y) = e^{-t+iy-(1-\varepsilon)x^2/2} \end{cases}$$

Then

$$\begin{aligned} \int_{[0, T] \times \tilde{\omega}} \left| \sum a_n v_n(x) e^{iny - \lambda_n t} \right|^2 dt dx dy \\ = \int_{[0, T] \times \tilde{\omega}} \left| \sum_{n>0} a_n w_n(x) e^{-\rho_n t} z_x(t, y)^n \right|^2 dt dx dy. \end{aligned}$$

Remark (lemma)

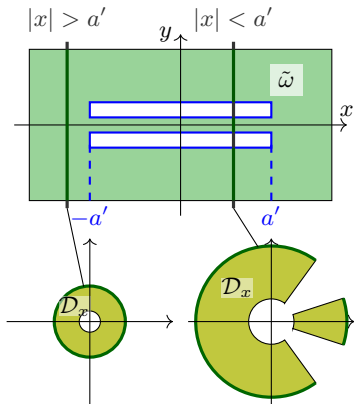
The eigenfunction v_n of $-\partial_x^2 + (nx)^2$ for the eigenvalue is closed to the eigenfunction of same operator on \mathbb{R} for the eigenvalue n , *i.e.*

$$v_n \text{ closed to } \left(\frac{n}{2\pi}\right)^{1/4} e^{-nx^2/2} \quad \text{and} \quad \lambda_n \text{ closed to } n.$$

Negative result : sketch of proof

- Denoting $\mathcal{D}_x = \{e^{-(1-\varepsilon)x^2/2}e^{-t+iy}, 0 < t < T, (x, y) \in \tilde{\omega}\}$, we get

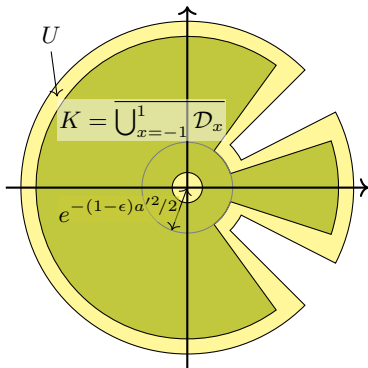
$$\int_{[0, T] \times \tilde{\omega}} \left| \sum_{n>0} a_n w_n(x) e^{-\rho_n t} z_x(t, y)^n \right|^2 dt dx dy$$
$$= \int_{-1}^1 \int_{\mathcal{D}_x} \left| \sum_{n>0} a_n w_n(x) e^{-\rho_n t} z^{n-1} \right|^2 d\lambda(z) dx.$$



Negative result : sketch of proof

- Since ρ_n, w_n are closed to 0, 1,

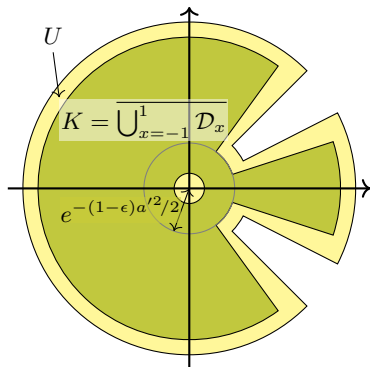
$$\int_{-1}^1 \left| \sum_{n>N} a_n w_n(x) e^{-\rho_n t} z^{n-1} \right|_{L^\infty(\mathcal{D}_x)}^2 dx \leq C \int_{-1}^1 \left| \sum_{n>N} a_n z^{n-1} \right|_{L^\infty(U)}.$$



Negative result : sketch of proof

Thus

$$\int_{D(0, e^{-T})} \left| \sum_{n>0} a_n z^{n-1} \right|^2 d\lambda(z) \leq C \left| \sum_{n>N} a_n z^{n-1} \right|_{L^\infty(U)}.$$



Negative result : sketch of proof

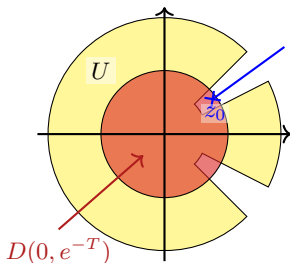
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Let $z_0 \in D(0, e^{-T}) \setminus \bar{U}$

and

$$f : z \in \mathbb{C} \setminus z_0[1, +\infty)z \mapsto (z - z_0)^{-1}.$$



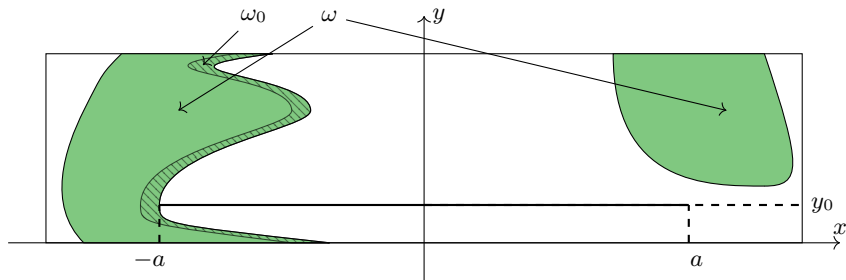
Proposition (Runge's theorem)

Let U be a connected and simply connected open subset of \mathbb{C} , and let f be a holomorphic function on U . There exists a sequence (\tilde{p}_k) of polynomials that converges uniformly on every compact subsets of U to f .

Then, the family $p_k(z) := z^{N+1} \tilde{p}_k(z)$ is a counter example to the inequality on entire polynomials.

□

Minimal time



Corollary ($T_0 = a^2/2$)

Assume that there exist $\varepsilon > 0$ and $\gamma \in C^0([0, 1], \Omega)$ with $\gamma(0) \in (-1, 1) \times \{0\}$ and $\gamma(1) \in (-1, 1) \times \{\pi\}$ such that $\omega_0 := \{z \in \Omega, \text{distance}(z, \text{Range}(\gamma)) < \varepsilon\} \subset \omega$.

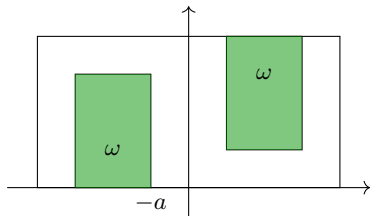
Assume that some $y_0 \in (0, \pi)$, $\{(x, y_0), -a < x < a\}$ is disjoint from $\bar{\omega}$ where

$$a := \sup_{(x,y) \in \Omega \setminus \omega_0} \{|x| : \exists x_0 \in (-1, 1), |x| < |x_0|, \text{sgn}(x) = \text{sgn}(x_0), (x_0, y) \in \omega_0\}.$$

One has

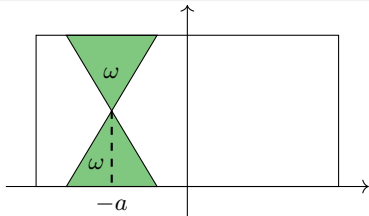
- If $T > a^2/2$, then the Grushin equation is **null controllable** in time T .
- If $T < a^2/2$, then the Grushin equation is **not null controllable** in time T .

Open problems



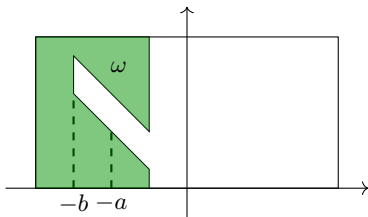
We can't go from the bottom boundary to the top boundary while staying inside ω .

$$T^* \geq a^2/2$$



A pinched domain.

$$T^* \geq a^2/2$$



A cave.

$$T^* \in [a^2/2, b^2/2]$$

Conclusion

- **Non exact controllability**
 - Regularizing effect of the heat equation
- **Approximate controllability**
 - Beauchard-Cannarsa-Guglielmi 2014
- **Minimal time null controllability**
 - Detailed description of the influence of the control region

Other example : Parabolic coupled systems

Consider

$$\begin{cases} \partial_t f_1 - \Delta f_1 + q(x)f_2 = 0, \\ \partial_t f_2 - \Delta f_2 = \mathbf{1}_\omega u, \\ f|_{\partial\Omega} = 0, \quad f(0) = f^0. \end{cases} \quad (1)$$

System (1) is approx. contr. if and only if

$$I_k(q) = \int_0^\pi q(x)\phi_k(x)^2 dx \neq 0, \quad \forall k > 0. \quad (2)$$

where $\phi_k := \sqrt{2/\pi} \sin(kx)$.

If (2) is satisfied and $\text{Supp}(q) \cap \omega = \emptyset$, then the minimal time of null controllability of system (1) is given by

$$T^* = \limsup \frac{-\log |I_k(q)|}{k^2}.$$

Ammar Khodja-Benabdallah-Gonzalez-Burgos-De Teresa, 2015

Question

Is there a **general theory** to determine the minimal time of null controllability for parabolic systems ?

$$\partial_t f + \mathcal{A}f = \mathcal{B}u$$

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Thanks for your attention !