

# Finite element method with local damage on the mesh

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Mathématiques de Paris



# Outline

① Problematic and previous results

② Local damage

③ Conditioning

④ Simulation

⑤ Conclusion

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# Framework

Consider the equation

$$\begin{cases} -\Delta u = f, \text{ in } \Omega \\ u = 0, \text{ on } \partial\Omega \end{cases}$$

i.e. the problem

$$\begin{cases} \text{Find } u \in H_0^1(\Omega) \text{ s.t. :} \\ \Leftrightarrow (\nabla u, \nabla v)_{L^2(\Omega)} = (f, v)_{L^2(\Omega)} \quad \forall v \in H_0^1(\Omega). \end{cases}$$

## General framework

$$\begin{cases} \text{Find } u \in V \text{ s.t. :} \\ a(u, v) = l(v) \quad \forall v \in V \end{cases}$$

where

- $l(\cdot)$  linear and continuous :  $|l(v)| \leq C_1 \|v\| \quad \forall v \in V$
- $a(\cdot, \cdot)$  bilinear continuous :  $|a(u, v)| \leq C_2 \|u\| \|v\| \quad \forall u, v \in V$
- $a(\cdot, \cdot)$  coercive :  $|a(v, v)| \geq C \|v\|^2 \quad \forall v \in V$

# Framework : Finite element method

Let  $V_h = \langle \phi_k \in V : k \in \{1, \dots, N\} \rangle \subset V$ .

System (1) will be approximate by

$$\begin{cases} \text{Find } u_h \in V_h \text{ s.t. :} \\ a(u_h, v_h) = l(v_h) \quad \forall v_h \in V_h \end{cases} \Leftrightarrow \begin{cases} \text{Find } U_h \in \mathbb{R}^N \text{ s.t. :} \\ A_h U_h = F_h \end{cases}$$

where

$$\begin{cases} A_h = a(\phi_k, \phi_j)_{kj} \\ F_h = l(\phi_k)_k \end{cases}$$

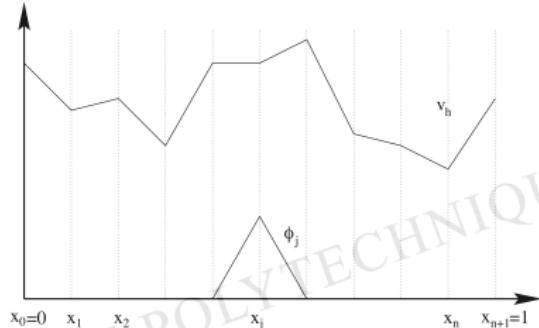
Thus

$$u_h = \sum U_{hk} \phi_k.$$

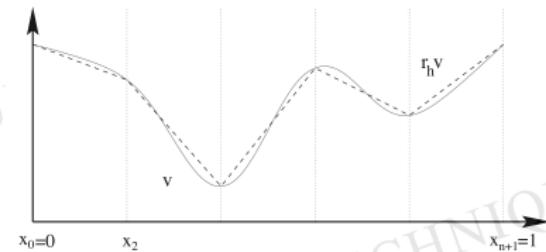
## Question

- How choose the functions  $\phi_k$  ?

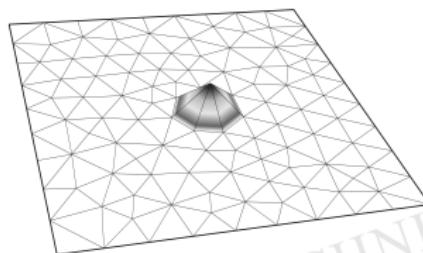
# Framework : Lagrange continuous finite element



Piecewise linear Lagrange FE order 1 ( $\mathbb{P}_1$ )



Lagrange interpolation



Order 1 ( $\mathbb{P}_1$ ), dimension 2

## Questions

- **Geometrical criterion** on the mesh to ensure the convergence ?

$$\|u_h - u\| \xrightarrow{h \rightarrow 0} 0$$

where  $h := \max_{\substack{\text{Cell} \\ \text{in mesh}}} \text{diam}(\text{Cell})$

- Optimal order in the *a priori* estimates

$$\begin{cases} |u - u_h|_1 \leq Ch|u|_2, \\ |u - u_h|_0 \leq Ch^2|u|_2. \end{cases}$$

- **Minimum angle condition**

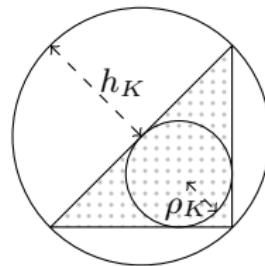
➢ dim 2 : Zlámal 68'

$$\min\{\text{angle}\} > \alpha > 0$$

- **Ciarlet condition**

➢ dim n : Ciarlet 78'

$$\frac{h_K}{\rho_K} < \gamma$$



- **Maximum angle condition**

➢ dim 2 : Babuska-Aziz 76', Barnhill-Gregory 76', Jamet 76'

➢ dim 3 : Krizek 92'

$$\max\{\text{angle}\} < \beta < \pi$$

# Idea of the proof

$$\begin{cases} \text{Find } u \in V \text{ s.t. :} \\ a(u, v) = l(v) \quad \forall v \in V \end{cases} \quad (1)$$

$$\begin{cases} \text{Find } u_h \in V_h \text{ s.t. :} \\ a(u_h, v_h) = l(v_h) \quad \forall v_h \in V_h \end{cases} \quad (2)$$

## Lemma (Local interpolation)

For each cell  $K \in \mathcal{T}_h$  and  $u \in H^2(K)$

$$|u - \mathcal{I}_h u|_{1,K} \leq C h |u|_{K,2},$$

where  $\mathcal{I}_h$  is the Lagrange interpolation operator.

## Lemma (Céa, see Ern-Guermond's book)

Let  $u$  and  $u_h$  solution to (1) and (2). Then

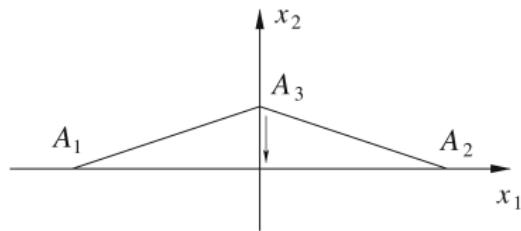
$$|u - u_h|_{1,\Omega} \leq C \inf_{v_h \in V_h} |u - v_h|_{1,\Omega}.$$

Thus

$$|u - u_h|_{1,\Omega} \leq C \inf_{v_h \in V_h} |u - v_h|_{1,\Omega} \leq C |u - \mathcal{I}_h u|_{1,\Omega} \leq C h |u|_{\Omega,2}.$$

## Counter-example [Babuska-Aziz 1976]

Let  $A_1 = (-1, 0)$ ,  $A_2 = (0, 1)$  and  $A_3 = (0, \varepsilon)$ .

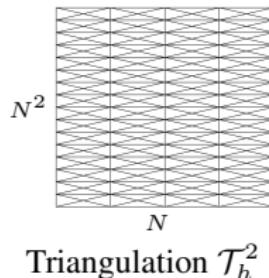
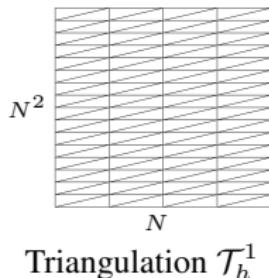


Consider  $u(x_1, x_2) = x_1^2$ . It holds

$$|u - \mathcal{I}_h u|_{1,K} \geq \frac{1}{\varepsilon}.$$

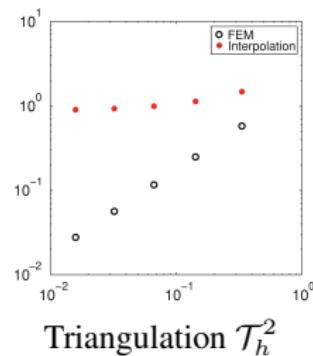
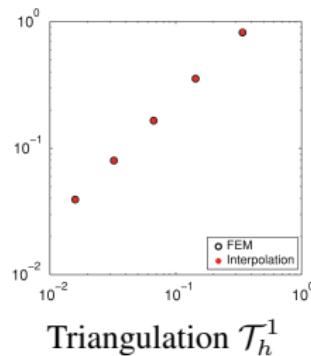
→ **large interpolation error**

# Inclusion of meshes [Hannukainen-Korotov-Krizek 2012]



Since  $V_h^1 \subset V_h^2$ ,

$$|u - u_h|_{1,\Omega} \leq C \inf_{v_h^2 \in V_h^2} |u - v_h^2|_{1,\Omega} \leq C \inf_{v_h^1 \in V_h^1} |u - v_h^1|_{1,\Omega} \leq C |u - \mathcal{I}_h^1 u|_{1,\Omega} \leq Ch |u|_{\Omega,2}.$$



# Outline

① Problematic and previous results

② Local damage

③ Conditioning

④ Simulations

⑤ Conclusion

# Local damage on the mesh

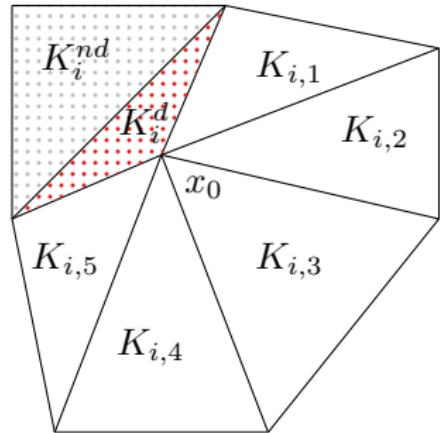
## Assumption 1

Let  $K_1^{deg}, \dots, K_I^{deg}$  be the degen. cells

$$h_{K_i^{deg}}/\rho_{K_i^{deg}} > c_0.$$

Assume that

- $h_{\mathcal{P}_i}/\rho_{\mathcal{P}_i} \leq c_1$ .
- $h_{K_{i,j}}/\rho_{K_{i,j}} \leq c_1$ .
- $h_{K_i^{nd}}/\rho_{K_i^{nd}} \leq c_1$ .
- $\tilde{\mathcal{P}}_i \cap \tilde{\mathcal{P}}_j = \emptyset$
- $\#\tilde{\mathcal{P}}_i \leq M$



$$\mathcal{P}_i := K_i^d \cup K_i^{nd}$$

$$\tilde{\mathcal{P}}_i := \mathcal{P}_i \cup_j K_{i,j}$$

## Theorem (D.-Lleras-Lozinski 2018)

Let  $u \in V$  and  $u_h \in V_h$  be the solutions to continuous and discrete Systems.  
Then, under Assumption 1,

$$|u - u_h|_{1,\Omega} \leq Ch|u|_{2,\Omega}.$$

# Sketch of proof

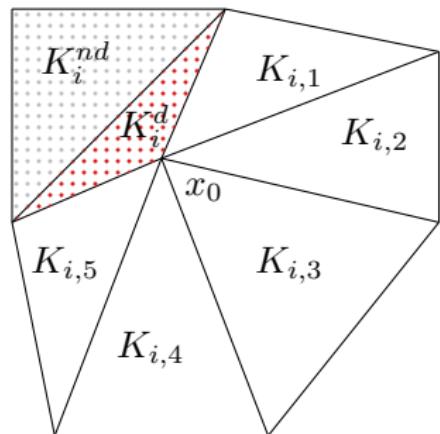
## Modified Lagrange interpolation operator

### Definition

For  $v \in H^2(\Omega)$ , defined  $\tilde{\mathcal{I}}_h(v) \in V_h$  s.t.

- $\tilde{\mathcal{I}}_h = \mathcal{I}_h$  on  $K \notin \mathcal{P}_i$
- $\tilde{\mathcal{I}}_h(x_0) = \text{Ext}(I_{h|K_i^{nd}})(x_0)$

where  $\mathcal{I}_h$  is the standard Lagrange interpolation operator.



### Proposition (D.-Lleras-Lozinski 2018)

Under Assumption 1, we have for all  $v \in H^2(\Omega) \cup H_0^1(\Omega)$

$$|v - \tilde{\mathcal{I}}_h(v)|_{1,\Omega} \leq Ch|v|_{2,\Omega}.$$

➤ Use the local interpolation estimate of  $\mathcal{I}_h$  on  $\mathcal{P}_i$

# Sketch of proof

Lemma (Céa, see Ern-Guermond's book)

Let  $u$  and  $u_h$  solution to (1) and (2). Then

$$|u - u_h|_{1,\Omega} \leq C \inf_{v_h \in V_h} |u - v_h|_{1,\Omega}.$$

Thus

$$|u - u_h|_{1,\Omega} \leq C \inf_{v_h \in V_h} |u - v_h|_{1,\Omega} \leq C |u - \tilde{\mathcal{I}}_h u|_{1,\Omega} \leq Ch|u|_{\Omega,2}.$$

□

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# Poor conditioning of the system matrix

Proposition (D.-Lleras-Lozinski 2018)

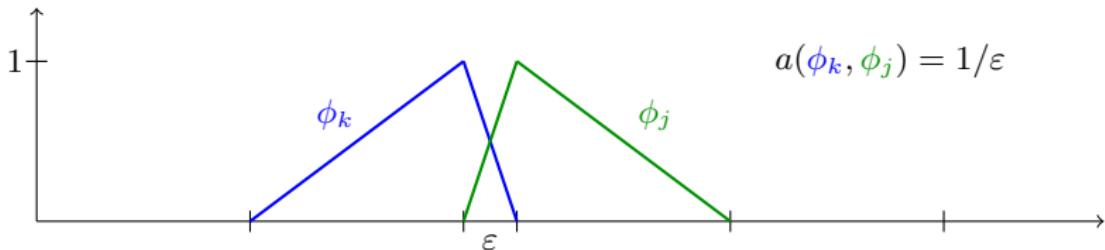
Suppose that the mesh  $\mathcal{T}_h$  contains a degenerate cell  $K^{deg}$

$$\rho_{K^{deg}} = \varepsilon, \quad h_{K^{deg}} \geq C_1 h.$$

Then the **conditioning number** associated to the bilinear form  $a$  in  $V_h$  satisfies

$$\kappa(\mathbf{A}) \geq \frac{C}{h\varepsilon}$$

Idea :



# An alternative scheme

We approximate

$$\begin{cases} \text{Find } u \in V \text{ s.t. :} \\ a(u, v) = l(v) \quad \forall v \in V \end{cases} \quad (1)$$

by the finite element formulation

$$\begin{cases} \text{Find } u_h \in V_h \text{ s.t. :} \\ a_h(u_h, v_h) = l(v_h) \quad \forall v_h \in V_h \end{cases} \quad (2)$$

where the bilinear form  $a_h$  is defined for all  $u_h, v_h \in V_h$  by

$$\begin{aligned} a_h(u_h, v_h) := & a_{\Omega_h^{nd}}(u_h, v_h) + \sum_i a_{\mathcal{P}_i}(\tilde{\mathcal{I}}_h u_h, \tilde{\mathcal{I}}_h v_h) \\ & + \sum_i \frac{1}{h_{\mathcal{P}_i}^2} ((\text{Id} - \tilde{\mathcal{I}}_h)u_h, (\text{Id} - \tilde{\mathcal{I}}_h)v_h)_{\mathcal{P}_i}, \end{aligned}$$

with  $\Omega_h^{nd} := (\cup \mathcal{P}_i)^c$ .

# A priori estimates and conditioning

Theorem (*A priori* estimate, D.-Lleras-Lozinski 2018)

Let  $\Omega$  convex and  $u \in V$ ,  $u_h \in V_h$  be the solutions to Systems (1) and (2).  
Then, under Assumption 1, we have ( $\varepsilon = 0$  if  $n = 3$ )

$$\begin{cases} |u - \tilde{\mathcal{I}}_h u_h|_{1,\Omega} \leq Ch^{1-\varepsilon} |u|_{2,\Omega}, \\ \|u - u_h\|_{0,\Omega} \leq Ch^{2-\varepsilon} |u|_{2,\Omega}. \end{cases}$$

Proposition (Conditioning, D.-Lleras-Lozinski 2018)

Suppose that Assumption 1 holds and the union of cells  $\omega_x$  attached to each node  $x$  of  $\mathcal{T}_h$  satisfies

$$c_1 h^n \leq |\omega_x| \leq c_2 h^n.$$

Then, the conditioning number of the matrix  $\mathbf{A}$  satisfies

$$\kappa(\mathbf{A}) \leq Ch^{-2}.$$

# Sketch of proof

Lemma (Coercivity of  $a_h$ )

$$a_h(v_h, v_h) \geq C \|v_h\|_{0,\Omega}^2 \quad \forall v_h \in V_h.$$

Lemma (Continuity of  $a_h$ )

$$a_h(u_h, v_h) \leq (C/h^2) \|u_h\|_{0,\Omega} \|v_h\|_{0,\Omega} \quad \forall u_h, v_h \in V_h.$$

$$\|\mathbf{A}\|_2 = \sup_{\mathbf{v} \in \mathbb{R}^N} \frac{(\mathbf{A}\mathbf{v}, \mathbf{v})}{|\mathbf{v}|_2^2} = \sup_{\mathbf{v} \in \mathbb{R}^N} \frac{a(v_h, v_h)}{|\mathbf{v}|_2^2} \leq Ch^n \sup_{v_h \in V_h} \frac{a(v_h, v_h)}{\|v_h\|_0^2} \leq Ch^{n-2}$$

$$\|\mathbf{A}^{-1}\|_2 = \sup_{\mathbf{v} \in \mathbb{R}^N} \frac{|\mathbf{v}|_2^2}{(\mathbf{A}\mathbf{v}, \mathbf{v})} = \sup_{\mathbf{v} \in \mathbb{R}^N} \frac{|\mathbf{v}|_2^2}{a(v_h, v_h)} \leq Ch^{-n} \sup_{v_h \in V_h} \frac{\|v_h\|_0^2}{a(v_h, v_h)} \leq Ch^{-n}$$

Thus

$$\kappa(\mathbf{A}) := \|\mathbf{A}\|_2 \|\mathbf{A}^{-1}\|_2 \leq C/h^2.$$

□

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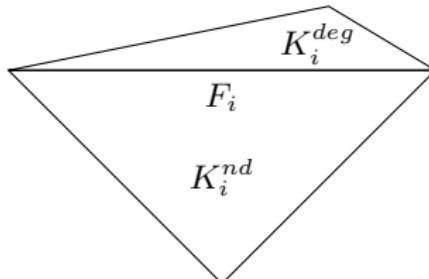
② Local damage

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# Equivalent formulation



Example of patch  $\mathcal{P}_i = K_i^{nd} \cup K_i^{deg}$ .

Proposition (D.-Lleras-Lozinski 2018)

For all  $u_h, v_h \in V_h$ , it holds

$$\begin{aligned} a_h(u_h, v_h) &= a_{\Omega_h^{nd}}(u_h, v_h) + \sum_i \frac{|\mathcal{P}_i|}{|K_i^{nd}|} a_{K_i^{nd}}(u_h, v_h) \\ &\quad + \kappa_n \sum_i \frac{|K_i^{deg}|^3}{h_{\mathcal{P}_i}^2 |F_i|^2} [\nabla u_h]_{F_i} \cdot [\nabla v_h]_{F_i} \end{aligned}$$

with  $\kappa_n := \frac{2n^2}{(n+1)(n+2)}$ .

# Simulation

Let  $\Omega := (0, 1) \times (0, 1)$  and  $f(x, y) = 2\pi^2 \sin(\pi x) \sin(\pi y)$ .

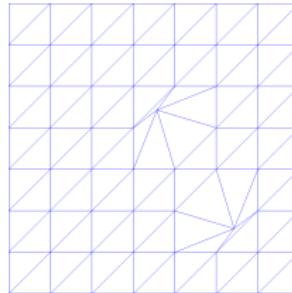
Consider the system

$$\begin{cases} \text{Find } u \in H_0^1(\Omega) \text{ s.t. :} \\ (\nabla u, \nabla v)_{L^2(\Omega)} = (f, v)_{L^2(\Omega)} \quad \forall v \in H_0^1(\Omega). \end{cases}$$

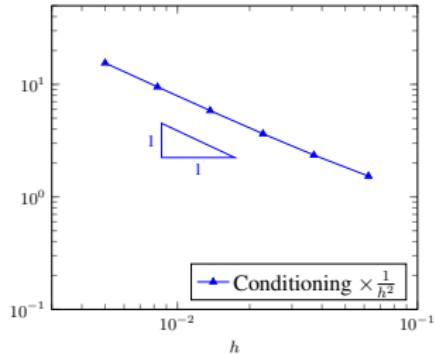
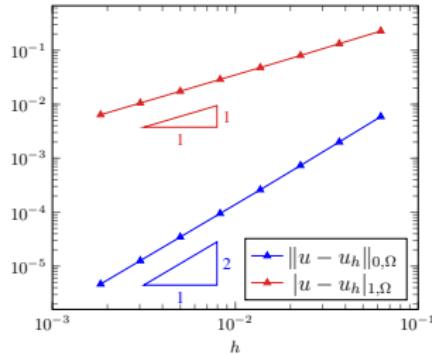
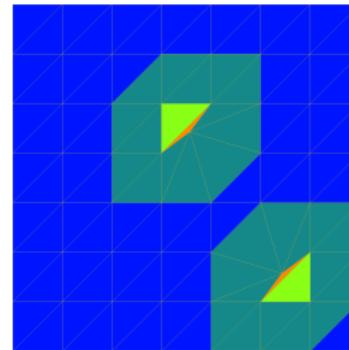
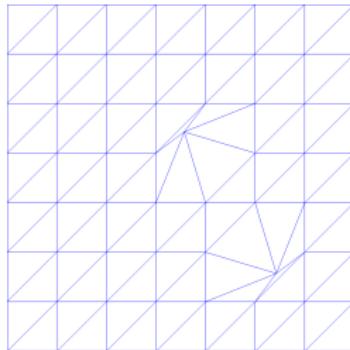
Exact solution :  $u(x, y) = \sin(\pi x) \sin(\pi y) \quad \forall (x, y) \in \Omega$ .

Cartesian meshes  $\mathcal{T}_h$  s.t. :

$$h_{K^{deg}} = h \text{ and } \rho_{K^{deg}} \sim h^2.$$

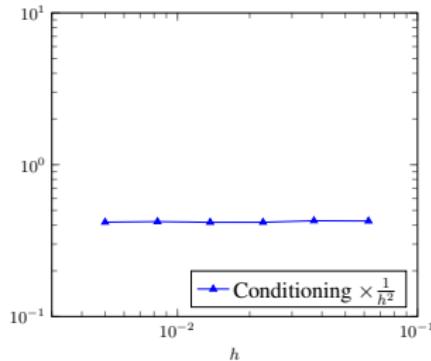
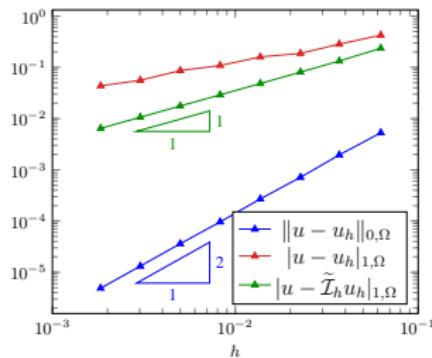
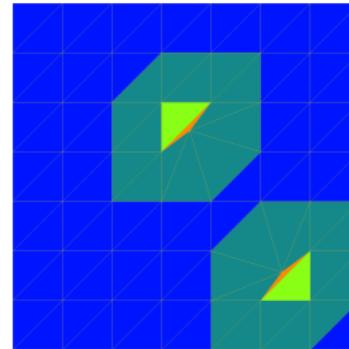
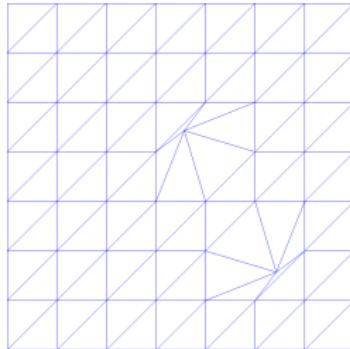


# Simulation



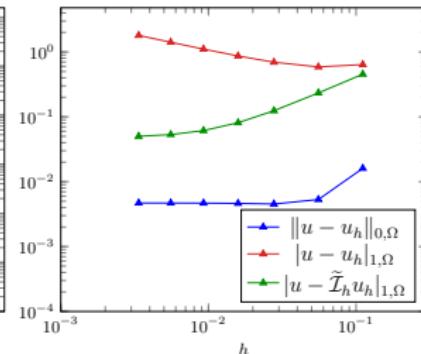
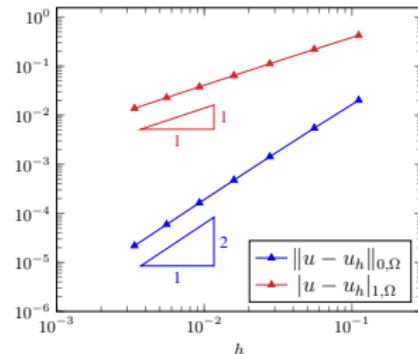
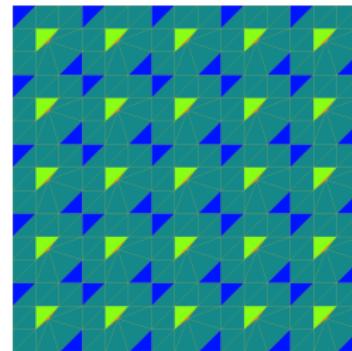
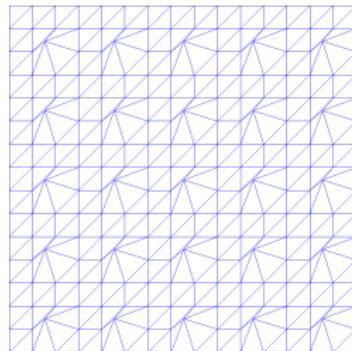
2 degenerated cells, standard scheme

# Simulation



2 degenerated cells, alternative scheme

# Simulation



5.5 % of degenerated cells standard scheme (left),  
alternative scheme (right)

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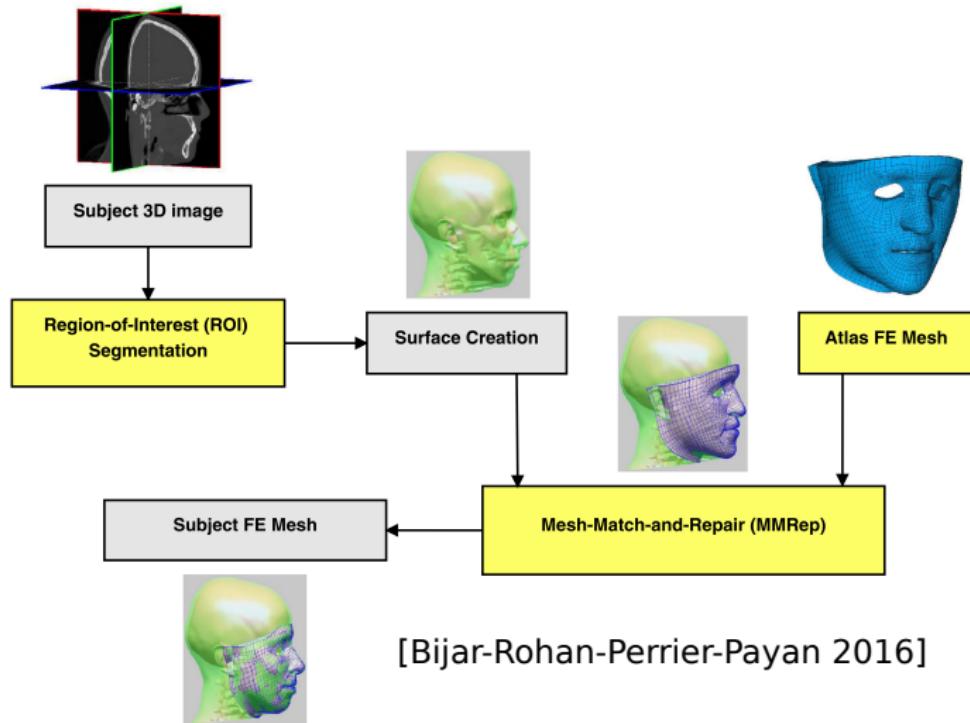
# Conclusion

- New sufficient geometrical conditions
  - Local damages : optimal convergence
- New operator of interpolation
  - Convergence of a operator of interpol.  $\neq$  convergence to the solution
- Alternative formulation for a good conditioning of the system matrix
  - Quasi optimal convergence
- Necessary and sufficient geometrical conditions remain open
  - Inclusion of meshes ?

## Application in biomechanics : generation of patient specific meshes

### Collaborations

- A. Lozinski  
➤ LMB, Besançon
- C. Lobos  
➤ Chile
- M. Bucki  
➤ Texisence, Grenoble
- V. Lleras  
➤ IMAG, Montpellier



[Bijar-Rohan-Perrier-Payan 2016]

## Fictitious domain method

Consider  $\Omega$  given by the levelset  $\Omega = \{\varphi < 0\}$  and

$$\begin{cases} -\Delta u = f & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{cases}$$

Consider the finite element approximation

$$\int_{\Omega_h^*} \nabla(\varphi \tilde{u}_h) \cdot \nabla(\varphi v_h) - \int_{\partial\Omega_h^*} \frac{\partial}{\partial n}(\varphi \tilde{u}_h) \varphi v_h + \underset{\text{Stab. Term}}{\text{ }} = \int_{\Omega_h^*} f \varphi v_h \quad \forall v_h \in V_h,$$

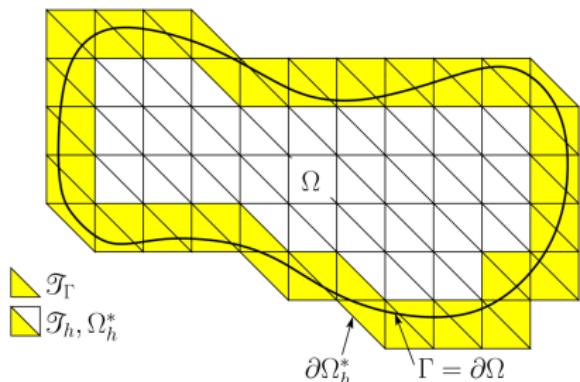
Then  $u_h := \tilde{u}_h \phi$ .

### Advantage

- No need to mesh
- Integration in the whole cells

### Collaboration

A. Lozinski, LMB (Besançon)





Thanks for your attention !