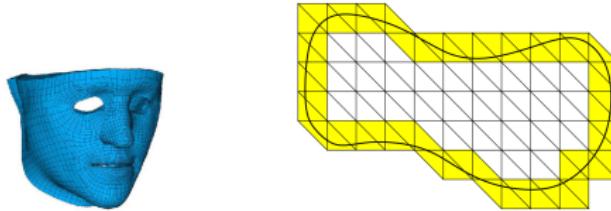


# Rule of the mesh in the Finite Element Method



M. Duprez<sup>1</sup>, V. Lleras<sup>2</sup> and A. Lozinski<sup>3</sup>

<sup>1</sup>CEntre de REcherche en MAthématiques de la DÉsision, Paris

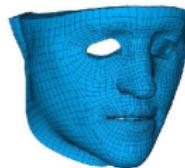
<sup>2</sup>IMAG, Montpellier

<sup>3</sup>Laboratoire de Mathématiques de Besançon

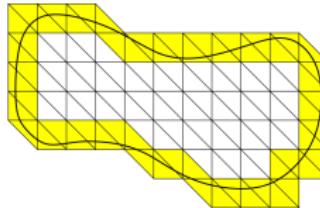
Séminaire d'Analyse et Probabilités

29/10/19

- ① Framework : Finite Element Method (FEM)
- ② Geometrical quality of a mesh



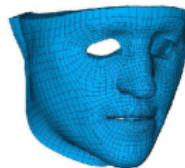
- ③ Mesh which is not conforming to the boundaries



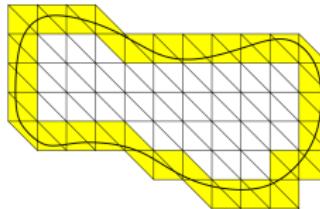
# Outline

## ① Finite Element Method (FEM)

## ② Geometrical quality of a mesh



## ③ Mesh which is not conforming to the boundaries



# Framework

## Considered equation

$$\begin{cases} -\Delta u = f, \text{ in } \Omega \\ u = 0, \text{ on } \partial\Omega \end{cases}$$

i.e. the problem

$$\begin{cases} \text{Find } u \in H_0^1(\Omega) \text{ s.t. :} \\ \Leftrightarrow (\nabla u, \nabla v)_{L^2(\Omega)} = (f, v)_{L^2(\Omega)} \quad \forall v \in H_0^1(\Omega). \end{cases}$$

## General framework

$$\begin{cases} \text{Find } u \in V \text{ s.t. :} \\ a(u, v) = l(v) \quad \forall v \in V \end{cases}$$

where

- $l(\cdot)$  **linear and continuous** :  $|l(v)| \leq C_1 \|v\| \quad \forall v \in V$
- $a(\cdot, \cdot)$  **bilinear continuous** :  $|a(u, v)| \leq C_2 \|u\| \|v\| \quad \forall u, v \in V$   
and **coercive** :  $|a(v, v)| \geq C \|v\|^2 \quad \forall v \in V$

# Framework : Finite element method

Let  $\mathbf{V}_h = \langle \phi_k \in V : k \in \{1, \dots, N\} \rangle \subset V$ .

System (1) will be approximate by

$$\left\{ \begin{array}{l} \text{Find } u_h \in V_h \text{ s.t. :} \\ a(u_h, v_h) = l(v_h) \quad \forall v_h \in V_h \end{array} \right. \Leftrightarrow \left\{ \begin{array}{l} \text{Find } U_h \in \mathbb{R}^N \text{ s.t. :} \\ A_h U_h = F_h \end{array} \right.$$

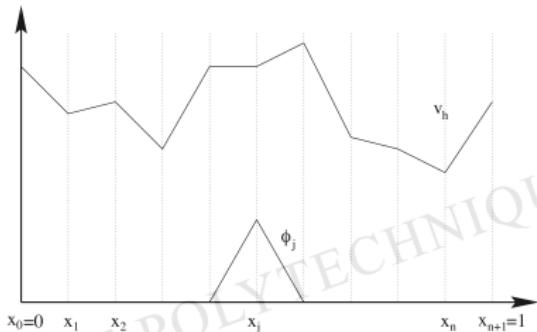
where

$$\left\{ \begin{array}{l} A_h = a(\phi_k, \phi_j)_{kj} \\ F_h = l(\phi_k)_k \end{array} \right.$$

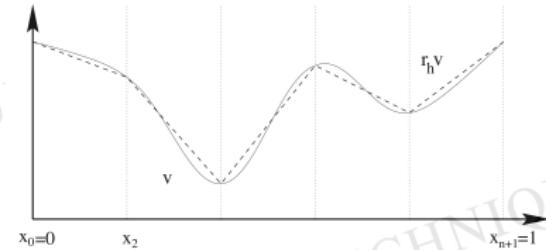
Thus

$$u_h = \sum U_{hk} \phi_k.$$

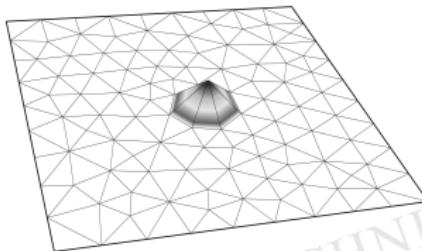
# Framework : Lagrange continuous finite element



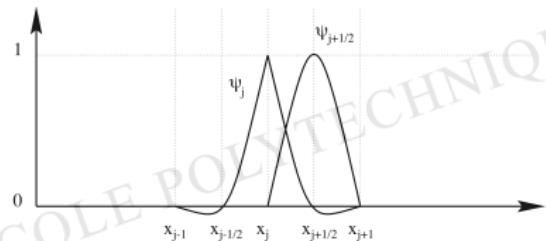
Piecewise linear Lagrange FE order 1 ( $\mathbb{P}_1$ )



Lagrange interpolation



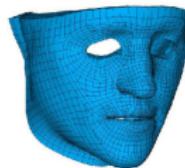
Order 1 ( $\mathbb{P}_1$ ), dimension 2



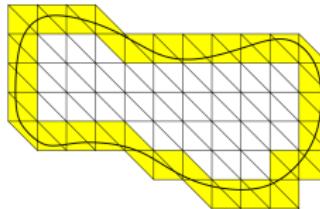
Order 2 ( $\mathbb{P}_2$ ), dimension 1

# Outline

- ① Framework : Finite Element Method (FEM)
- ② Geometrical quality of a mesh



- ③ Mesh which is not conforming to the boundaries



## Questions

- **Geometrical criterion** on the mesh to ensure the convergence ?

$$\|u_h - u\| \xrightarrow{h \rightarrow 0} 0$$

where  $h := \max_{\substack{\text{Cell} \\ \text{in mesh}}} \text{diam}(\text{Cell})$

- Optimal order in the *a priori* estimates for  $\mathbb{P}_1$

$$\begin{cases} |u - u_h|_1 \leq C h |u|_2, \\ |u - u_h|_0 \leq C h^2 |u|_2. \end{cases}$$

# Framework : geometrical condition

- **Minimum angle condition**

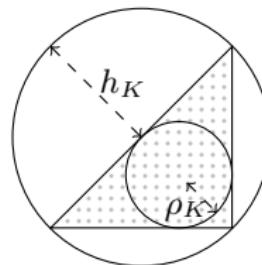
➢ dim 2 : Zlámal 68'

$$\min\{\text{angle}\} > \alpha > 0$$

- **Ciarlet condition**

➢ dim n : Ciarlet 78'

$$\frac{h_K}{\rho_K} < \gamma$$



- **Maximum angle condition**

➢ dim 2 : Babuska-Aziz 76', Barnhill-Gregory 76', Jamet 76'

➢ dim 3 : Krizek 92'

$$\max\{\text{angle}\} < \beta < \pi$$

- **Local damage**

➢ dim 2 : Kucera 2016

➢ dim n : Duprez-Lleras-Lozinski 2019

# Idea of the proof

$$\begin{cases} \text{Find } u \in V \text{ s.t. :} \\ a(u, v) = l(v) \quad \forall v \in V \end{cases} \quad (1)$$

$$\begin{cases} \text{Find } u_h \in V_h \text{ s.t. :} \\ a(u_h, v_h) = l(v_h) \quad \forall v_h \in V_h \end{cases} \quad (2)$$

Lemma (Local interpolation)

For each cell  $K \in \mathcal{T}_h$  and  $u \in H^2(K)$

$$|u - \mathcal{I}_h u|_{1,K} \leq C h |u|_{K,2},$$

where  $\mathcal{I}_h$  is the **Lagrange interpolation operator**.

Lemma (Céa, see Ern-Guermond's book)

Let  $u$  and  $u_h$  solution to (1) and (2). Then

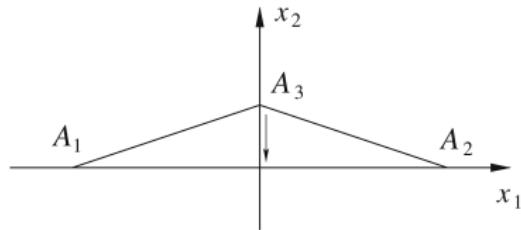
$$|u - u_h|_{1,\Omega} \leq C \inf_{v_h \in V_h} |u - v_h|_{1,\Omega}.$$

Thus

$$|u - u_h|_{1,\Omega} \leq C \inf_{v_h \in V_h} |u - v_h|_{1,\Omega} \leq C |u - \mathcal{I}_h u|_{1,\Omega} \leq C h |u|_{\Omega,2}.$$

## Counter-example [Babuska-Aziz 1976]

Let  $A_1 = (-1, 0)$ ,  $A_2 = (0, 1)$  and  $A_3 = (0, \varepsilon)$ .

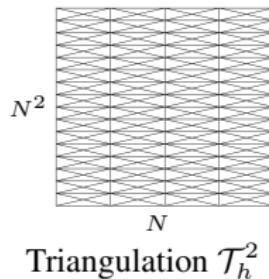
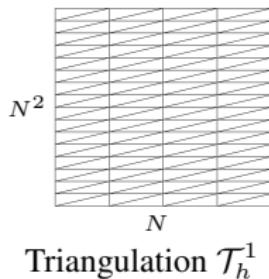


Consider  $u(x_1, x_2) = x_1^2$ . It holds

$$|u - \mathcal{I}_h u|_{1,K} \geq \frac{1}{\varepsilon}.$$

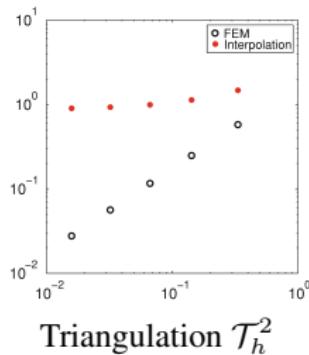
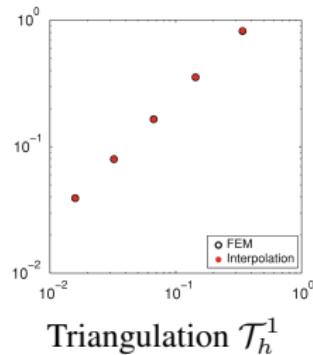
→ **large interpolation error**

# Inclusion of meshes [Hannukainen-Korotov-Krizek 2012]



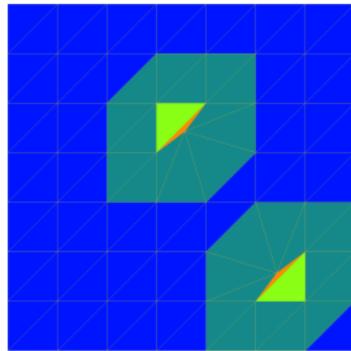
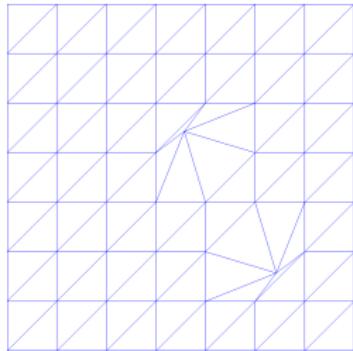
Since  $\mathbf{V}_h^1 \subset \mathbf{V}_h^2$ ,

$$|u - u_h^2|_{1,\Omega} \leq C \inf_{v_h^2 \in V_h^2} |u - v_h^2|_{1,\Omega} \leq C \inf_{v_h^1 \in V_h^1} |u - v_h^1|_{1,\Omega} \leq C |u - \mathcal{I}_h^1 u|_{1,\Omega} \leq Ch |u|_{\Omega,2}.$$



# Local damage on the mesh : example

Assume the degenerated cells are isolated :



# Local damage on the mesh : exact assumption

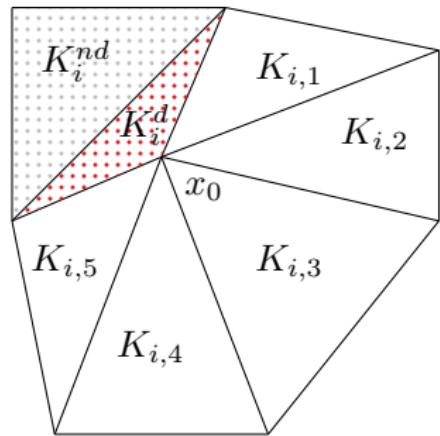
## Assumption

Let  $K_1^{deg}, \dots, K_I^{deg}$  be the degen. cells

$$h_{K_i^{deg}}/\rho_{K_i^{deg}} > c_0.$$

Assume that

- $h_{\mathcal{P}_i}/\rho_{\mathcal{P}_i} \leq c_1$ .
- $h_{K_{i,j}}/\rho_{K_{i,j}} \leq c_1$ .
- $h_{K_i^{nd}}/\rho_{K_i^{nd}} \leq c_1$ .
- $\tilde{\mathcal{P}}_i \cap \tilde{\mathcal{P}}_j = \emptyset$
- $\#\tilde{\mathcal{P}}_i \leq M$



$$\mathcal{P}_i := K_i^d \cup K_i^{nd}$$

$$\tilde{\mathcal{P}}_i := \mathcal{P}_i \cup_j K_{i,j}$$

## Theorem (D.-Lleras-Lozinski 2019)

Let  $u \in V$  and  $u_h \in V_h$  be the solutions to continuous and discrete Systems.  
Then, under Assumption 1,

$$|u - u_h|_{1,\Omega} \leq Ch|u|_{2,\Omega} \quad \text{and} \quad |u - u_h|_{0,\Omega} \leq Ch^2|u|_{2,\Omega}.$$

# Sketch of proof

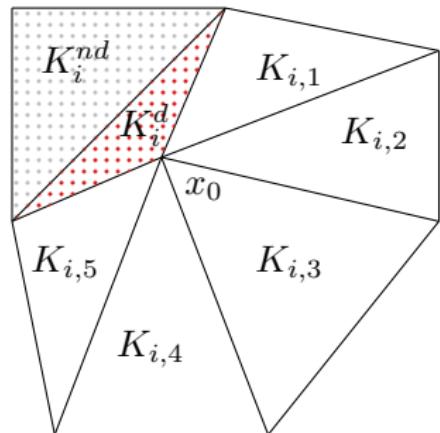
## Modified Lagrange interpolation operator

### Definition

For  $v \in H^2(\Omega)$ , defined  $\tilde{\mathcal{I}}_h(v) \in V_h$  s.t.

- $\tilde{\mathcal{I}}_h = \mathcal{I}_h$  on  $K \notin \mathcal{P}_i$
- $\tilde{\mathcal{I}}_h(x_0) = \text{Ext}(I_{h|K_i^{nd}})(x_0)$

where  $\mathcal{I}_h$  is the standard Lagrange interpolation operator.



### Proposition (D.-Lleras-Lozinski 2019)

Under Assumption 1, we have for all  $v \in H^2(\Omega) \cup H_0^1(\Omega)$

$$|v - \tilde{\mathcal{I}}_h(v)|_{1,\Omega} \leq Ch|v|_{2,\Omega}.$$

➤ Use the local interpolation estimate of  $\mathcal{I}_h$  on  $\mathcal{P}_i$

# Sketch of proof

Proposition (D.-Lleras-Lozinski 2019)

*Under Assumption 1, we have for all  $v \in H^2(\Omega) \cup H_0^1(\Omega)$*

$$|v - \tilde{\mathcal{I}}_h(v)|_{1,\Omega} \leq Ch|v|_{2,\Omega}.$$

Lemma (Céa, see Ern-Guermond's book)

*Let  $u$  and  $u_h$  solution to (1) and (2). Then*

$$|u - u_h|_{1,\Omega} \leq C \inf_{v_h \in V_h} |u - v_h|_{1,\Omega}.$$

Thus

$$|u - u_h|_{1,\Omega} \leq C \inf_{v_h \in V_h} |u - v_h|_{1,\Omega} \leq C|u - \tilde{\mathcal{I}}_h u|_{1,\Omega} \leq Ch|u|_{\Omega,2}.$$

□

# Poor conditioning of the system matrix

Proposition (D.-Lleras-Lozinski 2019)

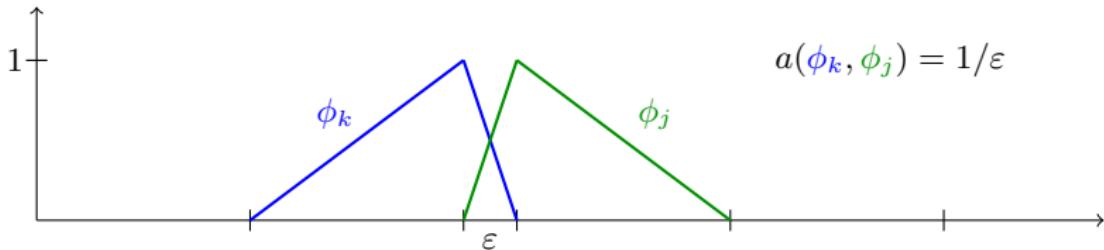
Suppose that the mesh  $\mathcal{T}_h$  contains a degenerate cell  $K^{deg}$

$$\rho_{K^{deg}} = \varepsilon, \quad h_{K^{deg}} \geq C_1 h.$$

Then the **conditioning number** associated to the bilinear form  $a$  in  $V_h$  satisfies

$$\kappa(\mathbf{A}) := \|\mathbf{A}\|_2 \|\mathbf{A}^{-1}\|_2 \geq \frac{C}{h\varepsilon}$$

**Idea :**



# An alternative scheme

We approximate

$$\begin{cases} \text{Find } u \in V \text{ s.t. :} \\ a(u, v) = l(v) \quad \forall v \in V \end{cases} \quad (1)$$

by the finite element formulation

$$\begin{cases} \text{Find } u_h \in V_h \text{ s.t. :} \\ a_h(u_h, v_h) = l(v_h) \quad \forall v_h \in V_h \end{cases} \quad (2)$$

where the bilinear form  $a_h$  is defined for all  $u_h, v_h \in V_h$  by

$$\begin{aligned} a_h(u_h, v_h) := & a_{\Omega_h^{nd}}(u_h, v_h) + \sum_i a_{\mathcal{P}_i}(\tilde{\mathcal{I}}_h u_h, \tilde{\mathcal{I}}_h v_h) \\ & + \sum_i \frac{1}{h_{\mathcal{P}_i}^2} ((\text{Id} - \tilde{\mathcal{I}}_h)u_h, (\text{Id} - \tilde{\mathcal{I}}_h)v_h)_{\mathcal{P}_i}, \end{aligned}$$

with  $\Omega_h^{nd} := (\cup \mathcal{P}_i)^c$ .

# A priori estimates and conditioning

Theorem (*A priori* estimate, D.-Lleras-Lozinski 2019)

Let  $\Omega$  convex and  $u \in V$ ,  $u_h \in V_h$  be the solutions to Systems (1) and (2).  
Then, under Assumption 1, we have ( $\varepsilon = 0$  if  $n = 3$ )

$$\begin{cases} |u - u_h|_{1,\Omega} \leq C_\varepsilon h^{1-\varepsilon} |u|_{2,\Omega}, \\ \|u - u_h\|_{0,\Omega} \leq C_\varepsilon h^{2-\varepsilon} |u|_{2,\Omega}. \end{cases}$$

Proposition (Conditioning, D.-Lleras-Lozinski 2019)

Suppose that Assumption 1 holds and the union of cells  $\omega_x$  attached to each node  $x$  of  $\mathcal{T}_h$  satisfies

$$c_1 h^n \leq |\omega_x| \leq c_2 h^n.$$

Then, the conditioning number of the matrix  $\mathbf{A}$  satisfies

$$\kappa(\mathbf{A}) := \|\mathbf{A}\|_2 \|\mathbf{A}^{-1}\|_2 \leq Ch^{-2}.$$

# Sketch of proof

Lemma (Coercivity of  $a_h$ )

$$a_h(v_h, v_h) \geq C \|v_h\|_{0,\Omega}^2 \quad \forall v_h \in V_h.$$

Lemma (Continuity of  $a_h$ )

$$a_h(u_h, v_h) \leq (C/h^2) \|u_h\|_{0,\Omega} \|v_h\|_{0,\Omega} \quad \forall u_h, v_h \in V_h.$$

$$\|\mathbf{A}\|_2 = \sup_{\mathbf{v} \in \mathbb{R}^N} \frac{(\mathbf{A}\mathbf{v}, \mathbf{v})}{\|\mathbf{v}\|_2^2} = \sup_{\mathbf{v} \in \mathbb{R}^N} \frac{a_h(v_h, v_h)}{\|\mathbf{v}\|_2^2} \leq Ch^n \sup_{v_h \in V_h} \frac{a_h(v_h, v_h)}{\|v_h\|_0^2} \leq Ch^{n-2}$$

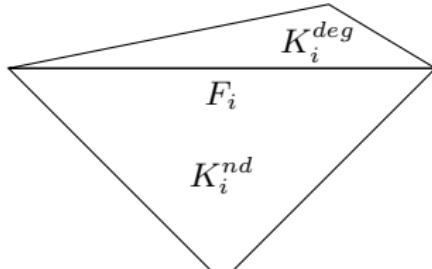
$$\|\mathbf{A}^{-1}\|_2 = \sup_{\mathbf{v} \in \mathbb{R}^N} \frac{\|\mathbf{v}\|_2^2}{(\mathbf{A}\mathbf{v}, \mathbf{v})} = \sup_{\mathbf{v} \in \mathbb{R}^N} \frac{\|\mathbf{v}\|_2^2}{a_h(v_h, v_h)} \leq Ch^{-n} \sup_{v_h \in V_h} \frac{\|v_h\|_0^2}{a_h(v_h, v_h)} \leq Ch^{-n}$$

Thus

$$\kappa(\mathbf{A}) := \|\mathbf{A}\|_2 \|\mathbf{A}^{-1}\|_2 \leq C/h^2.$$

□

# Equivalent formulation



Example of patch  $\mathcal{P}_i = K_i^{nd} \cup K_i^{deg}$ .

Proposition (D.-Lleras-Lozinski 2019)

For all  $u_h, v_h \in V_h$ , it holds

$$\begin{aligned} a_h(u_h, v_h) &= a_{\Omega_h^{nd}}(u_h, v_h) + \sum_i \frac{|\mathcal{P}_i|}{|K_i^{nd}|} a_{K_i^{nd}}(u_h, v_h) \\ &\quad + \kappa_n \sum_i \frac{|K_i^{deg}|^3}{h_{\mathcal{P}_i}^2 |F_i|^2} [\nabla u_h]_{F_i} \cdot [\nabla v_h]_{F_i} \end{aligned}$$

with  $\kappa_n := \frac{2n^2}{(n+1)(n+2)}$ .

# Simulation

Let  $\Omega := (0, 1) \times (0, 1)$  and  $f(x, y) = 2\pi^2 \sin(\pi x) \sin(\pi y)$ .

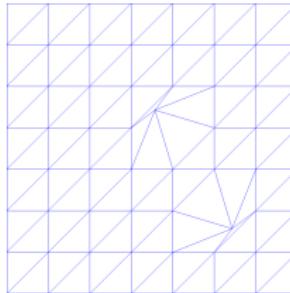
Consider the system

$$\begin{cases} \text{Find } u \in H_0^1(\Omega) \text{ s.t. :} \\ (\nabla u, \nabla v)_{L^2(\Omega)} = (f, v)_{L^2(\Omega)} \quad \forall v \in H_0^1(\Omega). \end{cases}$$

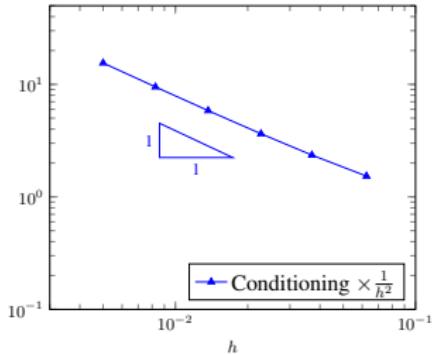
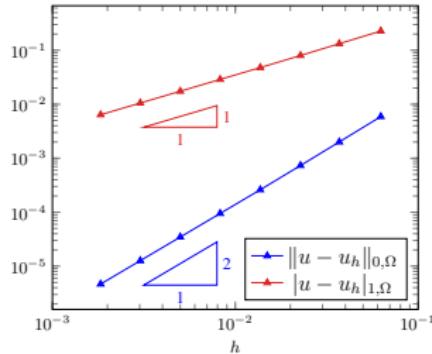
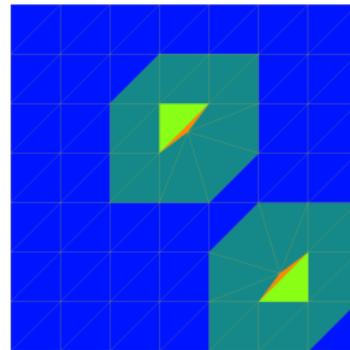
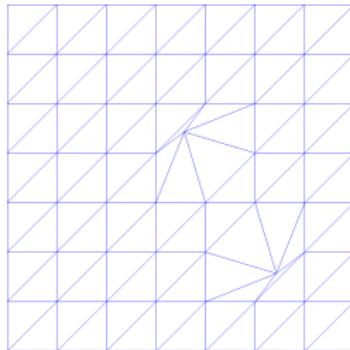
Exact solution :  $u(x, y) = \sin(\pi x) \sin(\pi y) \quad \forall (x, y) \in \Omega$ .

Cartesian meshes  $\mathcal{T}_h$  s.t. :

$$h_{K^{deg}} = h \text{ and } \rho_{K^{deg}} \sim h^2.$$

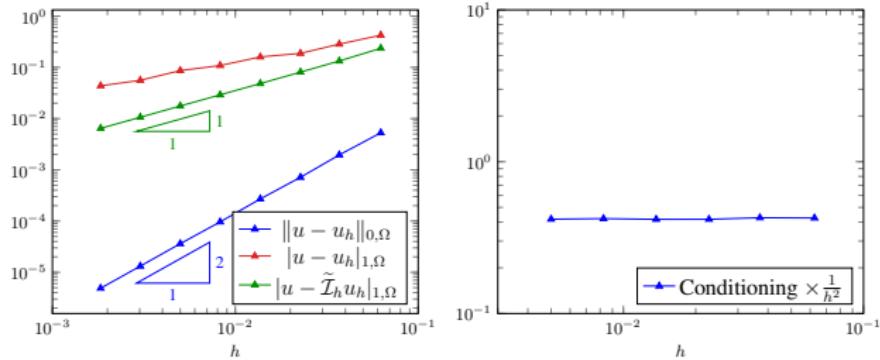
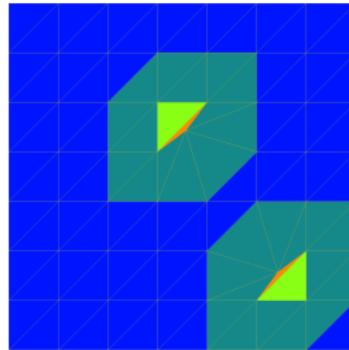
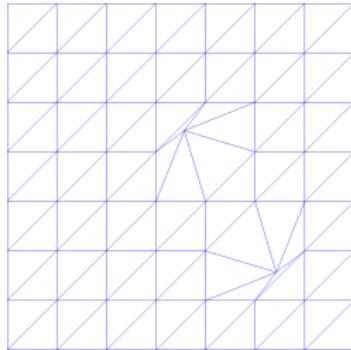


# Simulation



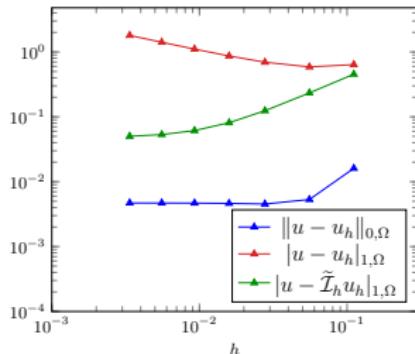
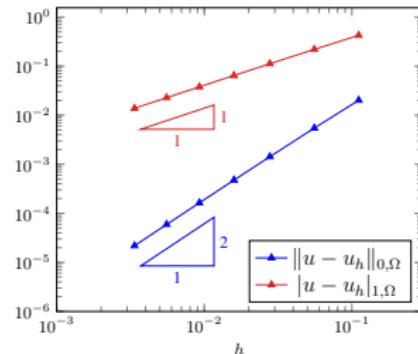
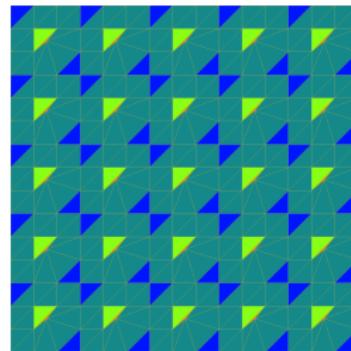
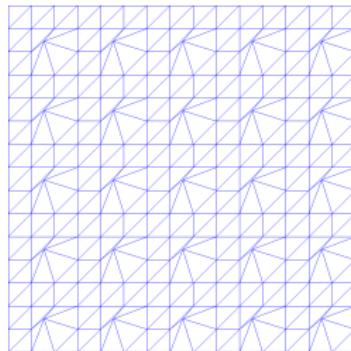
2 degenerated cells, standard scheme

# Simulation



2 degenerated cells, alternative scheme

# Simulation

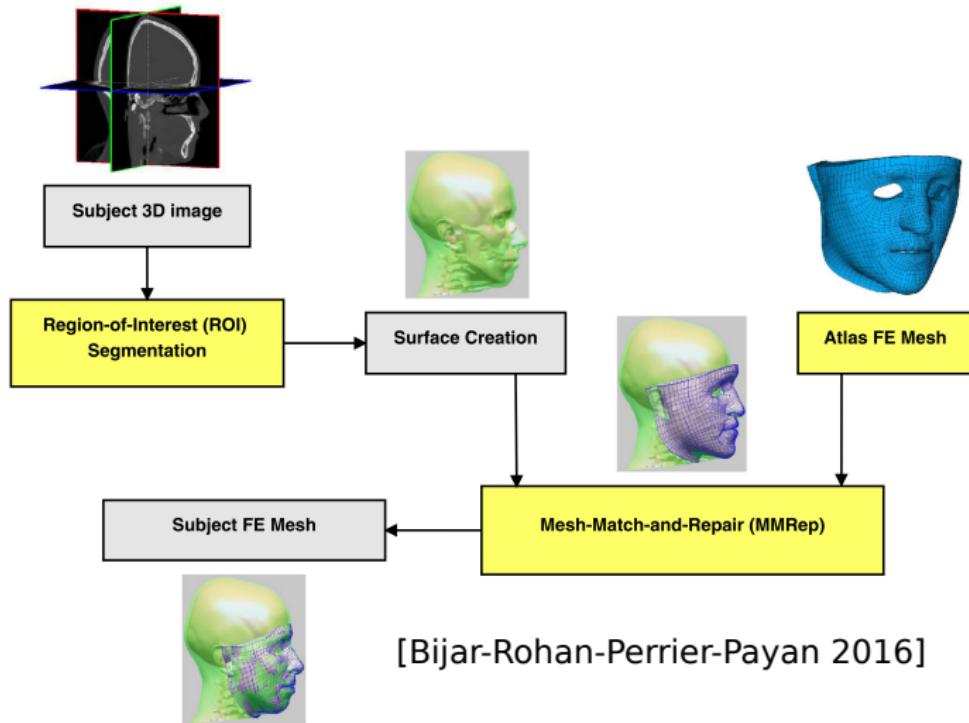


5.5 % of degenerated cells standard scheme (left),  
alternative scheme (right)

## Application in biomechanics : generation of patient specific meshes

### Collaborations

- A. Lozinski  
➤ LMB, Besançon
- C. Lobos  
➤ Chile
- M. Bucki  
➤ Texisence, Grenoble
- V. Lleras  
➤ IMAG, Montpellier



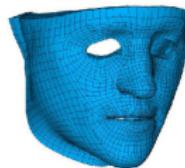
[Bijar-Rohan-Perrier-Payan 2016]

# Conclusion

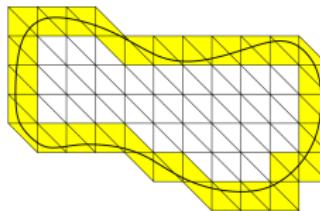
- **New sufficient geometrical conditions**
  - Local damages : optimal convergence
- New operator of **interpolation**
  - Convergence of a operator of interpol.  $\neq$  convergence to the solution
- **Alternative formulation** for a good conditioning of the system matrix
  - Quasi optimal convergence
- **Necessary and sufficient** geometrical conditions remain **open**
  - Inclusion of meshes ?

# Outline

- ① Framework : Finite Element Method (FEM)
- ② Geometrical quality of a mesh



- ③ Mesh which is not conforming to the boundaries



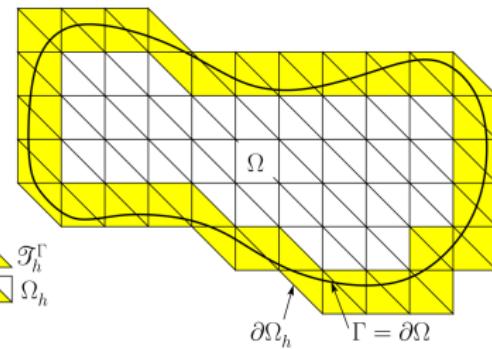
## Fictitious domain methods : non-matching meshes

### Previous results

- First work
  - Saul'ev 63'
- XFEM
  - Moes-Bechet-Tourbier 2006
  - Haslinger-Renard 2009
- CutFEM
  - Burman-Hansbo 2010-2014
  - Lozinski 2019

### Methods

- Extended finite element space
- Standard penalizations
- Nitsche penalizations
- **Ghost penalty**
- Lagrange multipliers



# Framework : previous results

**Lagrange multipliers approximated by  $\mathbb{P}_0$ -FE on the cut triangles  $\mathcal{T}_h^\gamma$  :**

Find  $u_h \in V_h$ ,  $\lambda_h \in W_h = \{\mu_h \in L^2(\Omega_h^\gamma) : \mu_{h|T} \in \mathbb{P}_0(T) \forall T \in \mathcal{T}_h^\Gamma\}$  :

$$\begin{aligned}\int_{\Omega} \nabla u_h \cdot \nabla v_h + \int_{\Gamma} \lambda_h v_h &= \int_{\Omega} f v_h \quad \forall v_h \in V_h \\ \int_{\Gamma} \mu_h u_h &= \sigma h \sum_{E \in \mathcal{T}_h^\gamma} [\lambda_h][\mu_h] \quad \forall \mu_h \in W_h\end{aligned}$$

➤ Burman-Hansbo 2010

**Difficulty :**

The actual formulation contain a **integral on the real boundary**.

# $\phi$ -FEM : formal approach

## Initial problem

Consider a domain  $\Omega$  and

$$\left\{ \begin{array}{ll} \text{Find } u \text{ s.t. :} \\ -\Delta u = f & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{array} \right.$$

## $\phi$ -FEM (formal) approach

Assume that  $\Omega$  and  $\Gamma$  are given by a **level-set** function  $\phi$  :

$$\Omega := \{\phi < 0\} \text{ and } \Gamma := \{\phi = 0\}.$$

Consider the problem

$$\left\{ \begin{array}{ll} \text{Find } v \text{ s.t. :} \\ -\Delta(\phi v) = f & \text{in } \Omega \end{array} \right.$$

Then  $u := \phi v$  is solution to the initial problem.

# $\phi$ -FEM : weak formulation

Assume that  $\Omega$  and  $\Gamma$  are given by a level-set function  $\phi$  :

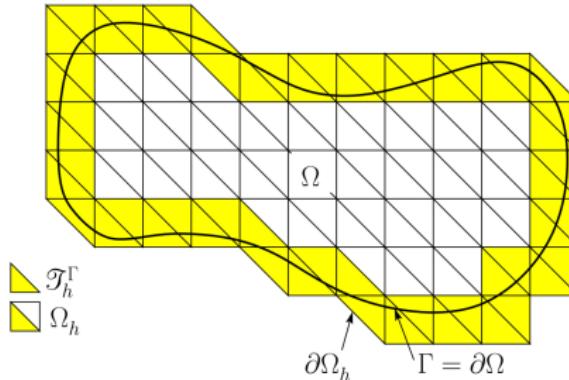
$$\Omega := \{\phi < 0\} \text{ and } \Gamma := \{\phi = 0\}.$$

Suppose that  $\phi$  is near  $\Gamma$  as the signed distance to  $\Gamma$ .

Consider the finite element approximation

$$\int_{\Omega_h} \nabla(\phi v_h) \cdot \nabla(\phi w_h) - \int_{\partial\Omega_h} \frac{\partial}{\partial n}(\phi v_h)\phi w_h + \text{Stab. Term} = \int_{\Omega_h} f\phi w_h \quad \forall w_h \in W_h,$$

Then  $u_h := v_h\phi$  as approximation of the initial problem.



# $\phi$ -FEM : a priori error estimates

Consider the finite element approximation :  $a_h(v_h, w_h) = l_h(w_h)$   $\forall w_h \in W_h$ ,  
where

$$\begin{cases} a_h(v_h, w_h) = \int_{\Omega_h} \nabla(\phi_h v_h) \cdot \nabla(\phi_h w_h) - \int_{\partial\Omega_h} \frac{\partial}{\partial n}(\phi_h v_h) \phi_h w_h + G_h^1(\tilde{u}_h, v_h) \\ l_h(w_h) = \int_{\Omega_h} f \phi_h w_h + G_h^2(w_h), \end{cases}$$

with  $\phi_h = I_h(\phi_h)$ ,  $G_h^1$  and  $G_h^2$  stands for the the **ghost penalty** given by

$$\begin{cases} G_h^1(v_h, w_h) = \sigma h \sum_{E \in \mathcal{F}_\Gamma} \int_E \left[ \frac{\partial}{\partial n}(\phi_h v_h) \right] \left[ \frac{\partial}{\partial n}(\phi_h w_h) \right] \\ \quad + \sigma h^2 \sum_{T \in \mathcal{T}_h^\Gamma} \int_T \Delta(\phi_h v_h) \Delta(\phi_h w_h) \\ G_h^2(w_h) = -\sigma h^2 \sum_{T \in \mathcal{T}_h^\Gamma} \int_T f \Delta(\phi_h w_h) \end{cases}$$

and

$$\begin{cases} \mathcal{T}_h^\Gamma = \{T \in \mathcal{T}_h : T \cap \Gamma_h \neq \emptyset\} \quad (\Gamma_h = \{\phi_h = 0\}); \\ \mathcal{F}_\Gamma = \{E \text{ (an internal edge of } \mathcal{T}_h) \text{ such that } \exists T \in \mathcal{T}_h : T \cap \Gamma_h \neq \emptyset \text{ and } E \in \partial T\}. \end{cases}$$

# $\phi$ -FEM : a priori error estimate

## Continuous problem

$$a(u, w) = l(w) \quad \forall w \in V$$

## Finite element formulation

$$a_h(v_h, w_h) = l_h(w_h) \quad \forall w_h \in V_h^{(k)} \subset V$$

Theorem (D.-Lozinski 2019)

Suppose that the mesh  $\mathcal{T}_h$  is uniform (with some weak assumptions), and  $f \in H^k(\Omega_h \cup \Omega)$ . Let  $u \in H^{k+2}(\Omega)$  be the continuous solution and  $w_h \in V_h^{(k)}$  be the discrete solution. Denoting  $u_h := \phi_h w_h$ , it holds

$$|u - u_h|_{1,\Omega \cap \Omega_h} \leq Ch^k \|f\|_{k,\Omega \cup \Omega_h}$$

with  $C = C(\phi)$ . Moreover, supposing  $\Omega \subset \Omega_h$

$$\|u - u_h\|_{0,\Omega} \leq Ch^{k+1/2} \|f\|_{k,\Omega_h}.$$

## $\phi$ -FEM : key lemmas

Lemma (Hardy inequality, D.-Lozinski 2019)

We assume that the domain  $\Omega$  is given by the level-set  $\phi$  regular enough. Then, for any  $u \in H^{k+1}(\mathcal{O})$  vanishing on  $\Gamma$ ,

$$\left\| \frac{u}{\phi} \right\|_{k,\mathcal{O}} \leq C \|u\|_{k+1,\mathcal{O}}.$$

Lemma (Local interpolation, Ern-Guermond's book)

For  $k \in \mathbb{N}^*$ , each cell  $K \in \mathcal{T}_h$  and  $u \in H^2(K)$

$$|u - \mathcal{I}_h u|_{1,K} \leq C h^k |u|_{K,k+1},$$

where  $\mathcal{I}_h$  is the Lagrange interpolation operator.

## Theorem (Conditioning)

Assume that  $\mathcal{T}_h$  is uniform (and satisfies the assumptions). Then the condition number  $\kappa(\mathbf{A}) := \|\mathbf{A}\|_2 \|\mathbf{A}^{-1}\|_2$  of the matrix  $\mathbf{A}$  associated to the bilinear form  $a_h$  on  $V_h^{(k)}$  satisfies

$$\kappa(\mathbf{A}) \leq Ch^{-2}.$$

Here,  $\|\cdot\|_2$  stands for the matrix norm associated to the vector 2-norm  $|\cdot|_2$ .

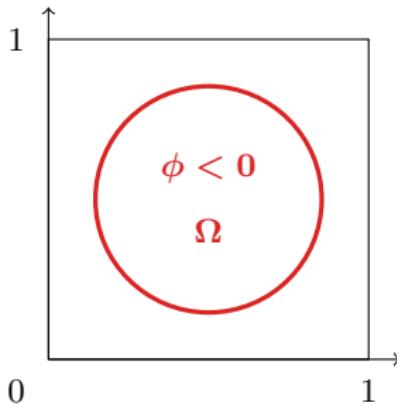
# $\phi$ -FEM : Simulations

Let  $\Omega$  be the circle of radius  $\sqrt{2}/4$  centered at the point  $(0.5, 0.5)$  and the surrounding domain  $\mathcal{O} = (0, 1)^2$ . The level-set function  $\phi$  giving this domain  $\Omega$  is taken as

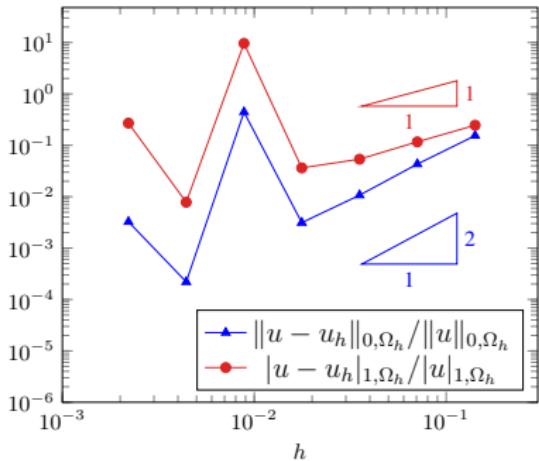
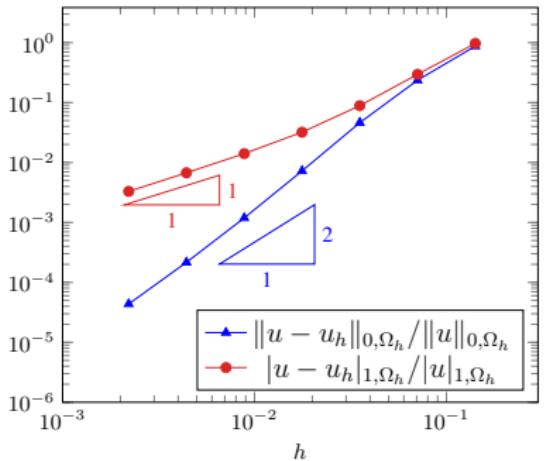
$$\phi(x, y) = (x - 1/2)^2 - (y - 1/2)^2 - 1/8.$$

We use  $\phi$ -FEM to solve numerically Poisson-Dirichlet problem with the exact solution given by

$$u(x, y) = \phi(x, y) \times \exp(x) \times \sin(2\pi y).$$

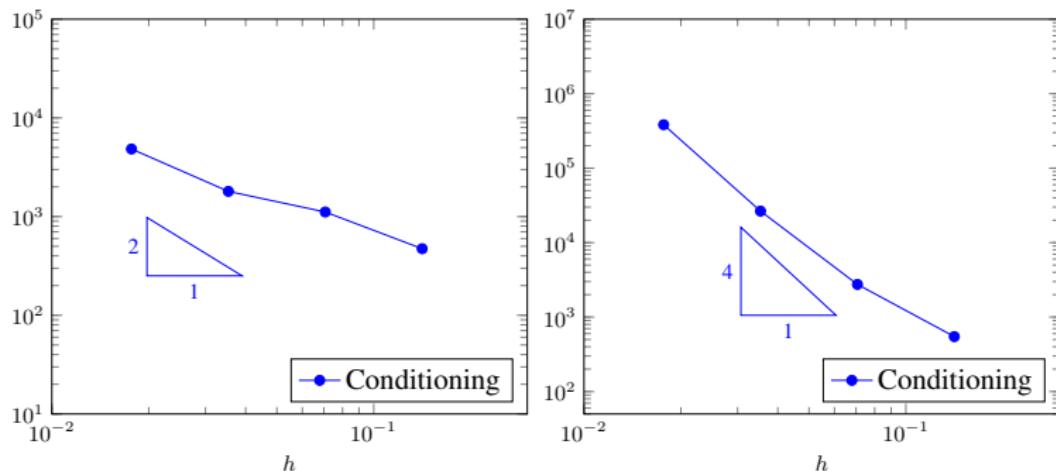


# $\phi$ -FEM : Simulations



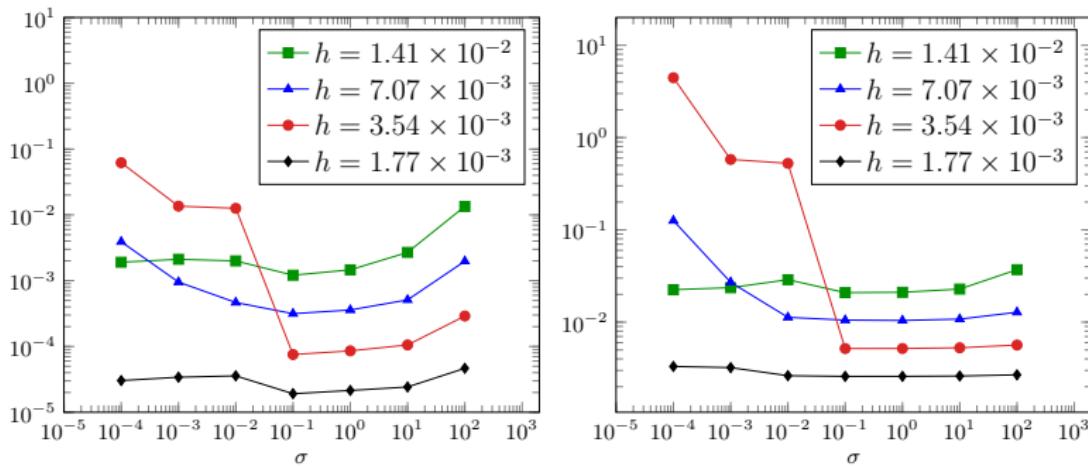
**FIGURE –** Relative errors of  $\phi$ -FEM for  $k = 1$ . Left :  $\phi$ -FEM with ghost penalty  $\sigma = 20$ ; Right :  $\phi$ -FEM without ghost penalty ( $\sigma = 0$ ).

# $\phi$ -FEM : Simulations



**FIGURE –** Condition numbers for  $\phi$ -FEM  $k = 1$ . Left :  $\phi$ -FEM with ghost penalty  $\sigma = 20$ ; Right :  $\phi$ -FEM without ghost penalty ( $\sigma = 0$ ).

# $\phi$ -FEM : Simulations



**FIGURE –** Influence of the ghost penalty parameter  $\sigma$  on the relative errors for  $\phi$ -FEM  $k = 1$ . Left :  $\|u - u_h\|_{0,\Omega_h} / \|u\|_{0,\Omega_h}$  ; Right :  $|u - u_h|_{1,\Omega_h} / |u|_{1,\Omega_h}$ .

# $\phi$ -FEM : Simulations

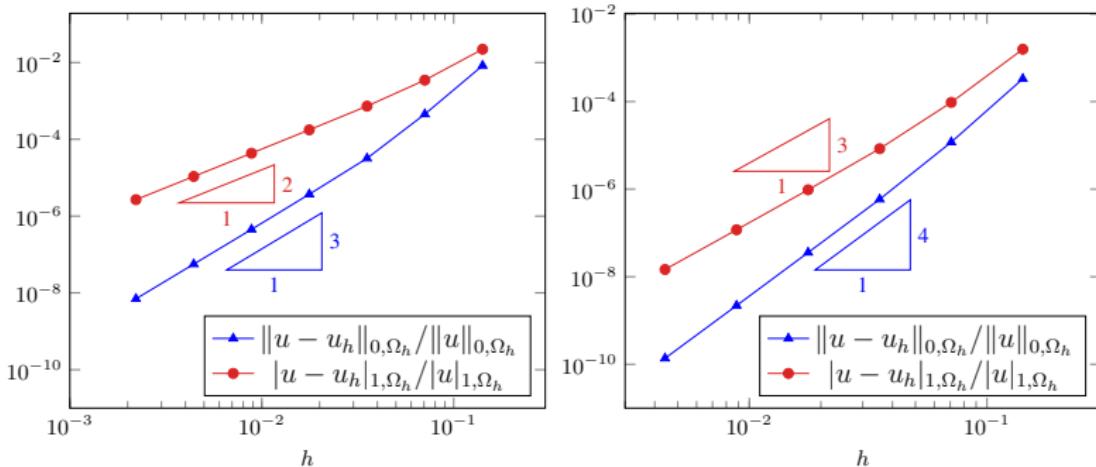
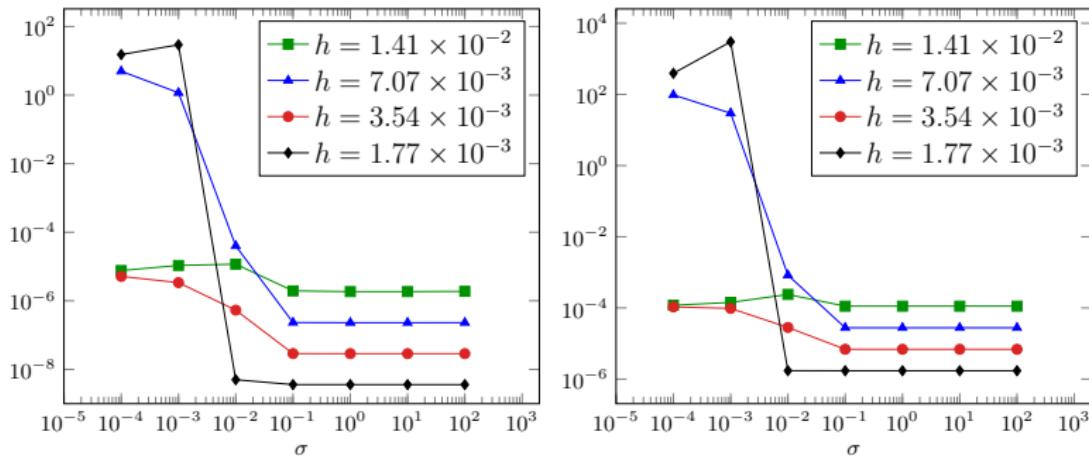


FIGURE – Relative errors of  $\phi$ -FEM. Left :  $k = 2$ ; Right :  $k = 3$ .

# $\phi$ -FEM : Simulations



**FIGURE –** Influence of the ghost penalty parameter  $\sigma$  on the relative errors for  $\phi$ -FEM and  $k = 2$ . Left :  $\|u - u_h\|_{0,\Omega} / \|u\|_{0,\Omega}$ ; Right :  $|u - u_h|_{1,\Omega} / |u|_{1,\Omega}$ .

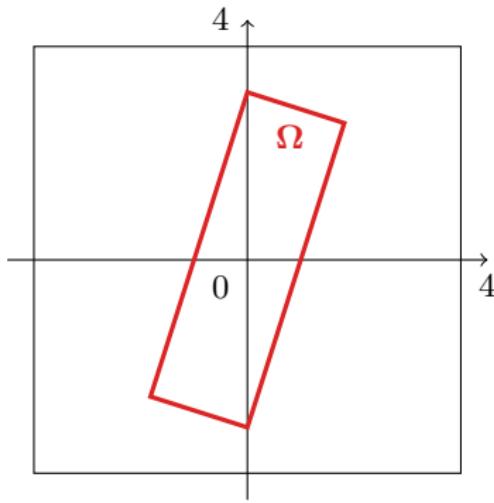
# $\phi$ -FEM : Simulations

We now choose domain  $\Omega$  given by the level-set

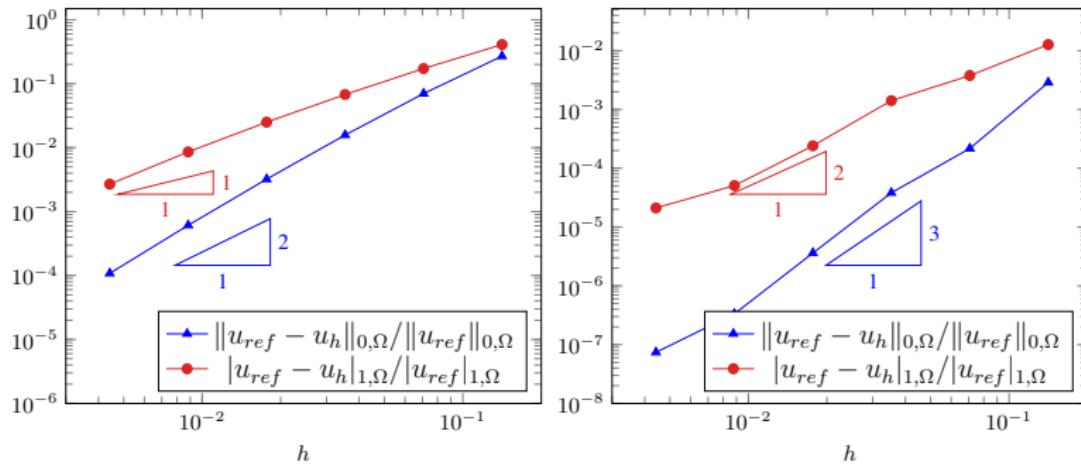
$$\phi(x, y) = -(y - \pi x - \pi) \times (y + x/\pi - \pi) \times (y - \pi x + \pi) \times (y + x/\pi + \pi).$$

It is thus the rectangle with corners  $\left(\frac{2\pi^2}{\pi^2+1}, \frac{\pi^3-\pi}{\pi^2+1}\right)$ ,  $(0, \pi)$ ,  $\left(-\frac{2\pi^2}{\pi^2+1}, -\frac{\pi^3-\pi}{\pi^2+1}\right)$ ,  $(0, -\pi)$ . We use  $\phi$ -FEM to solve numerically Poisson-Dirichlet problem in  $\Omega$  with the right-hand side given by

$$f(x, y) = 1.$$



# $\phi$ -FEM : Simulations



**FIGURE –** Relative errors of  $\phi$ -FEM. Left :  $k = 2$ ; Right :  $k = 3$ . The reference solution  $u_{ref}$  is computed by a standard FEM on a sufficiently fitted mesh on  $\Omega$ .

## Results

- **Optimal convergence** of  $\phi$ -FEM in the  $H^1$  semi-norm
- Quasi-optimal convergence of  $\phi$ -FEM in the  $L^2$  norm
  - Optimal convergence numerically
- Discrete problem **well conditioned**

## Perspectives

- **Neumann** or Robin boundary conditions
  - First results with a mixed formulation
- Dynamic equation : **heat equation**

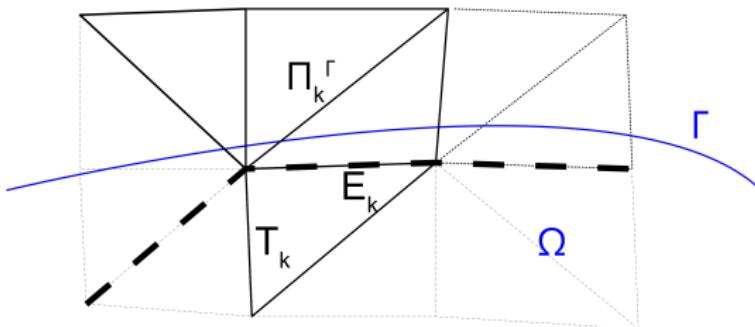
Thanks for your attention !

# $\phi$ -FEM : mesh assumptions

## Assumption

The approximate boundary  $\Gamma_h$  can be covered by element patches  $\{\Pi_i\}_{i=1,\dots,N_\Pi}$  having the following properties :

- Each patch  $\Pi_i$  is a connected set composed of a mesh element  $T_i \in \mathcal{T}_h \setminus \mathcal{T}_h^\Gamma$  and some mesh elements cut by  $\Gamma_h$ . More precisely,  $\Pi_i = T_i \cup \Pi_i^\Gamma$  with  $\Pi_i^\Gamma \subset \mathcal{T}_h^\Gamma$  containing at most  $M$  mesh elements;
- $\mathcal{T}_h^\Gamma = \cup_{i=1}^{N_\Pi} \Pi_i^\Gamma$ ;
- $\Pi_i$  and  $\Pi_j$  are disjoint if  $i \neq j$ .



## Assumption

The boundary  $\Gamma$  can be covered by open sets  $\mathcal{O}_i$ ,  $i = 1, \dots, I$  and one can introduce on every  $\mathcal{O}_i$  local coordinates  $\xi_1, \dots, \xi_d$  with  $\xi_d = \phi$  such that all the partial derivatives  $\partial^\alpha \xi / \partial x^\alpha$  and  $\partial^\alpha x / \partial \xi^\alpha$  up to order  $k + 1$  are bounded by some  $C_0 > 0$ . Moreover,  $|\phi| \geq m$  on  $\mathcal{O} \setminus \cup_{i=1, \dots, I} \mathcal{O}_i$  with some  $m > 0$ .